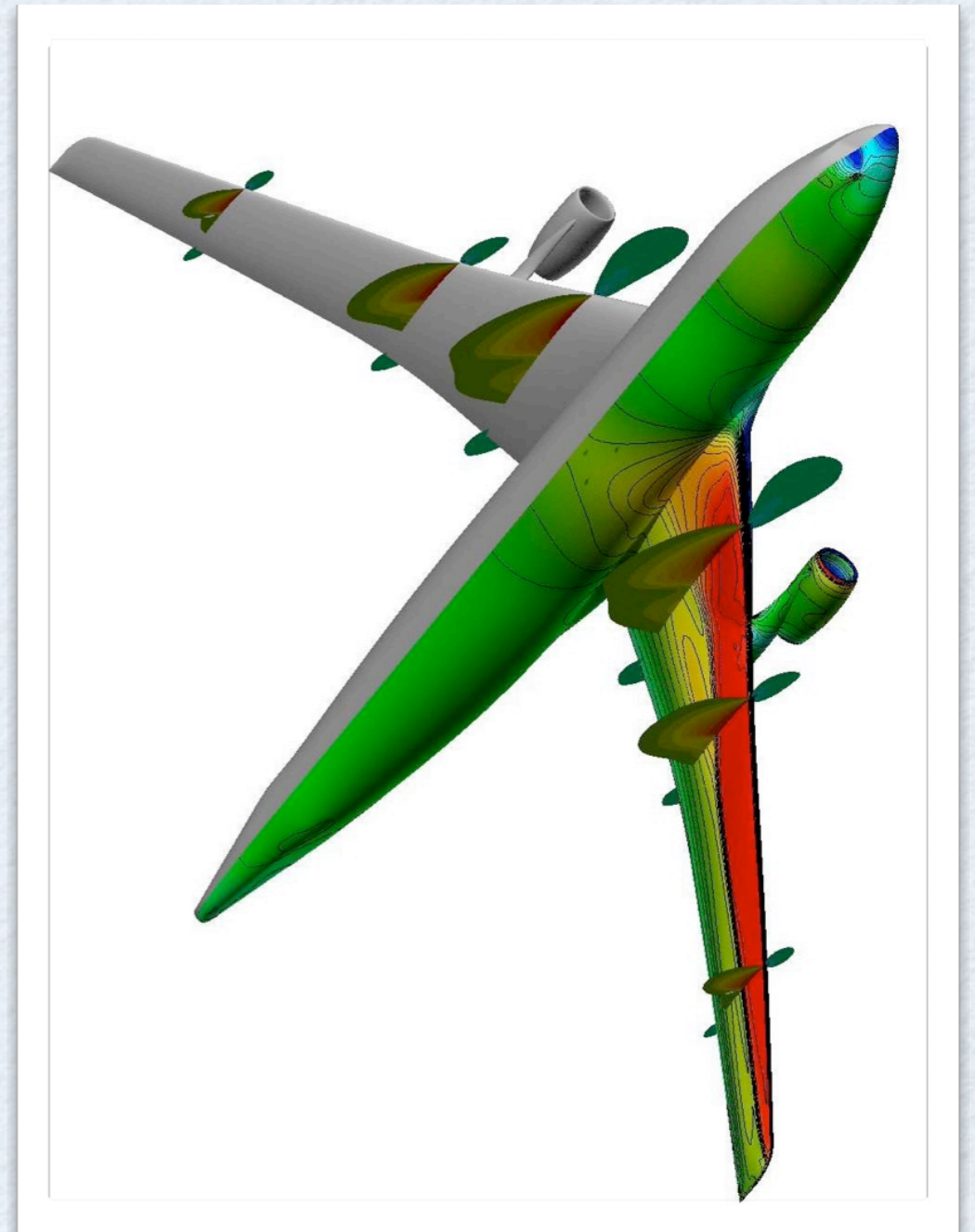


CFD in Manufacturing and Medical Applications

Petros Koumoutsakos
Chair of Computational Science

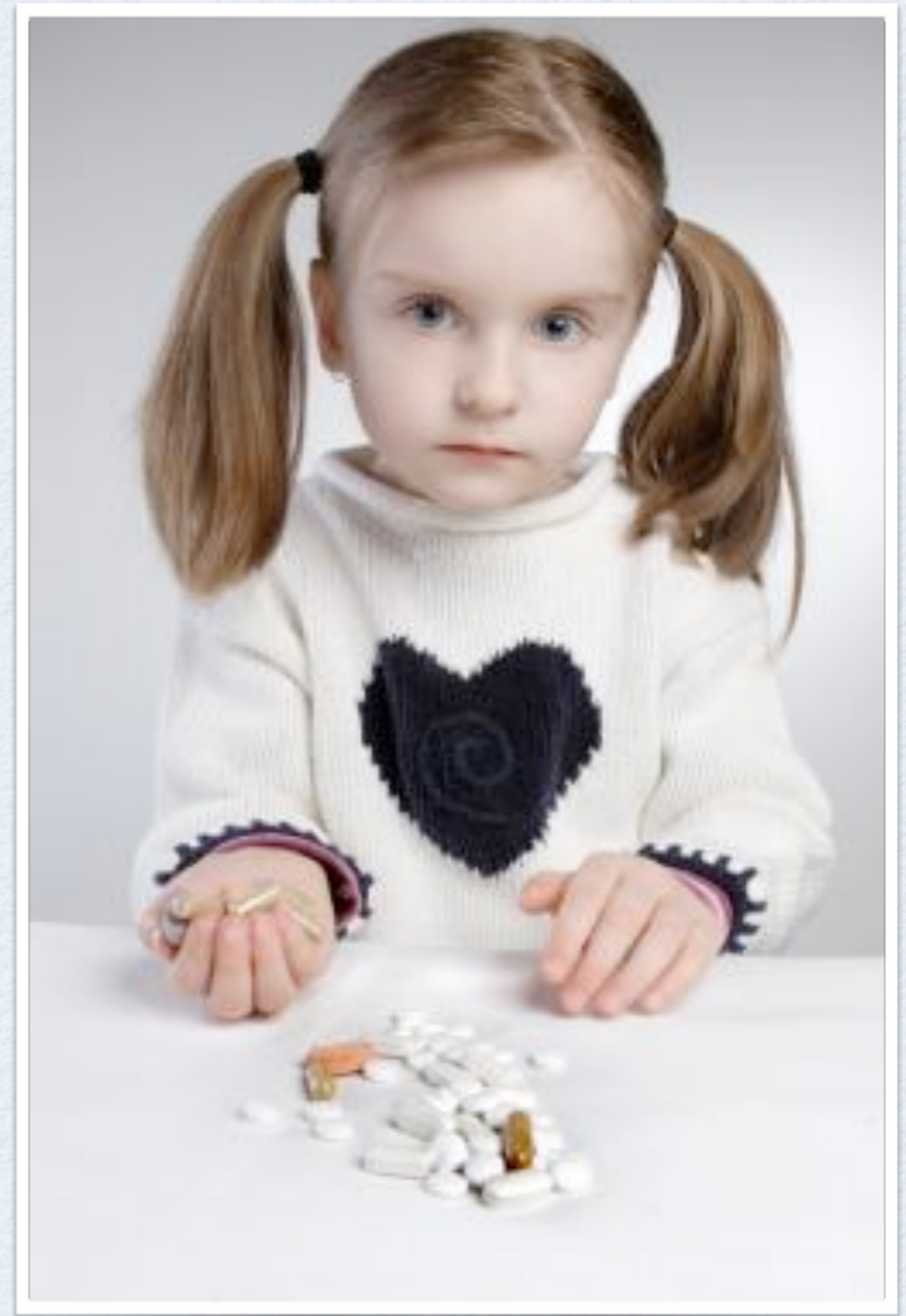
Modeling and Technology

- No aircraft is flown without having been designed with complex, mechanistic simulations

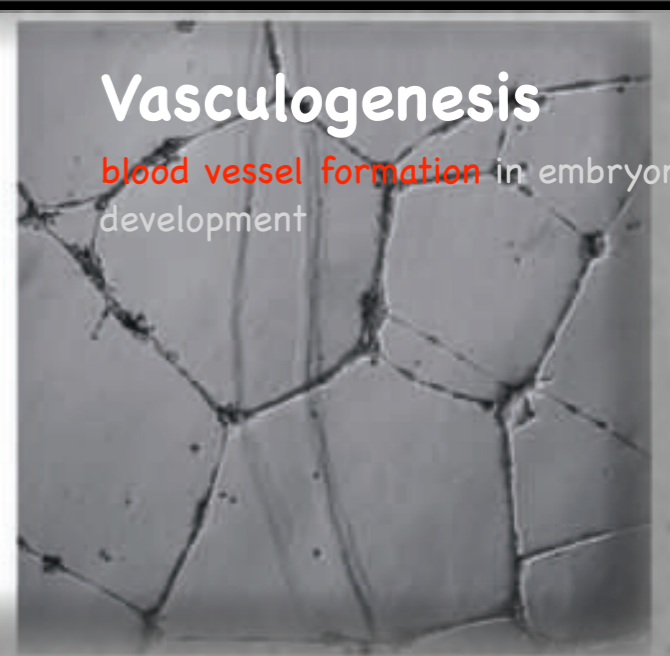
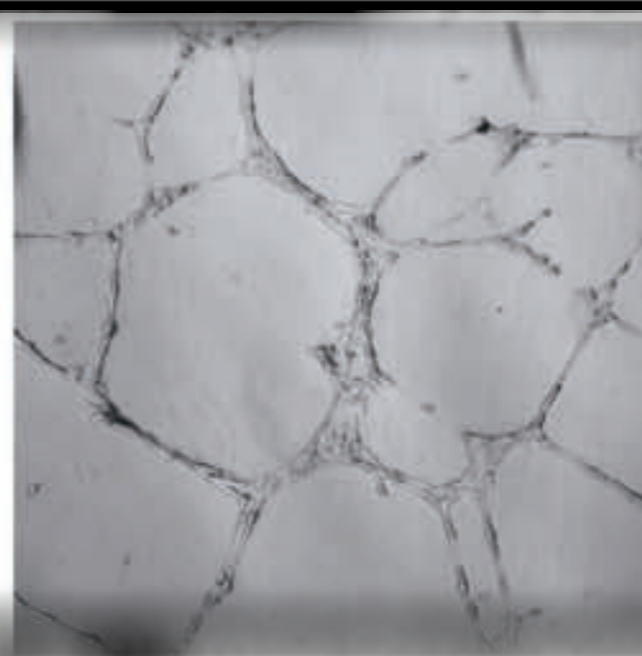
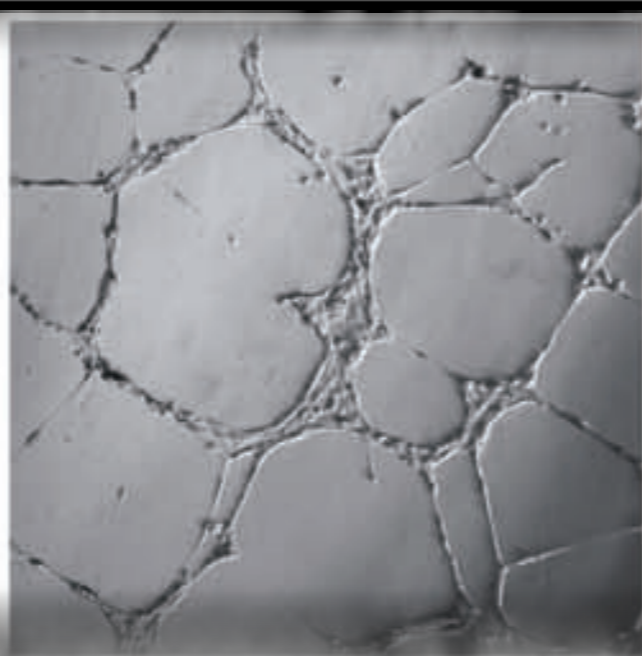
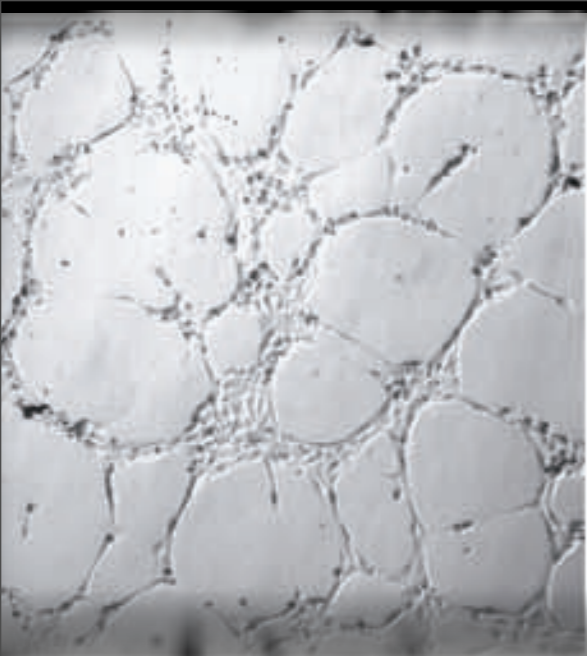


Modeling and Medicine

- Heuristics and Data
- Models ?



Dreamstime.com



Vasculogenesis

blood vessel formation in embryonic development

R. M. H. MERKS, S. V. BRODSKY, M. S. GOLIGORSKY, S. A. NEWMAN, AND J. A. GLAZIER. CELL ELONGATION IS KEY TO IN SILICO REPLICATION OF IN VITRO VASCULOGENESIS AND SUBSEQUENT REMODELING. DEVELOPMENTAL BIOLOGY, 289(1): 44-54, 2006.



Crown Breakup - marangoni instability

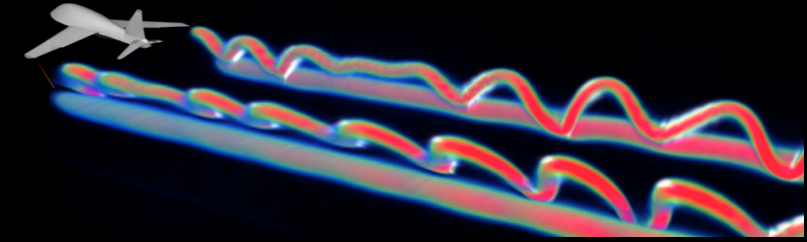
drop impact onto an ethanol sheet

[2] S. T. THORODDSEN, T. G. ETOH, AND K. TAKEHARA. CROWN BREAKUP BY MARANGONI INSTABILITY. J. FLUID MECH., 557(-1):63-72, 2006.

Τα πάντα ρει

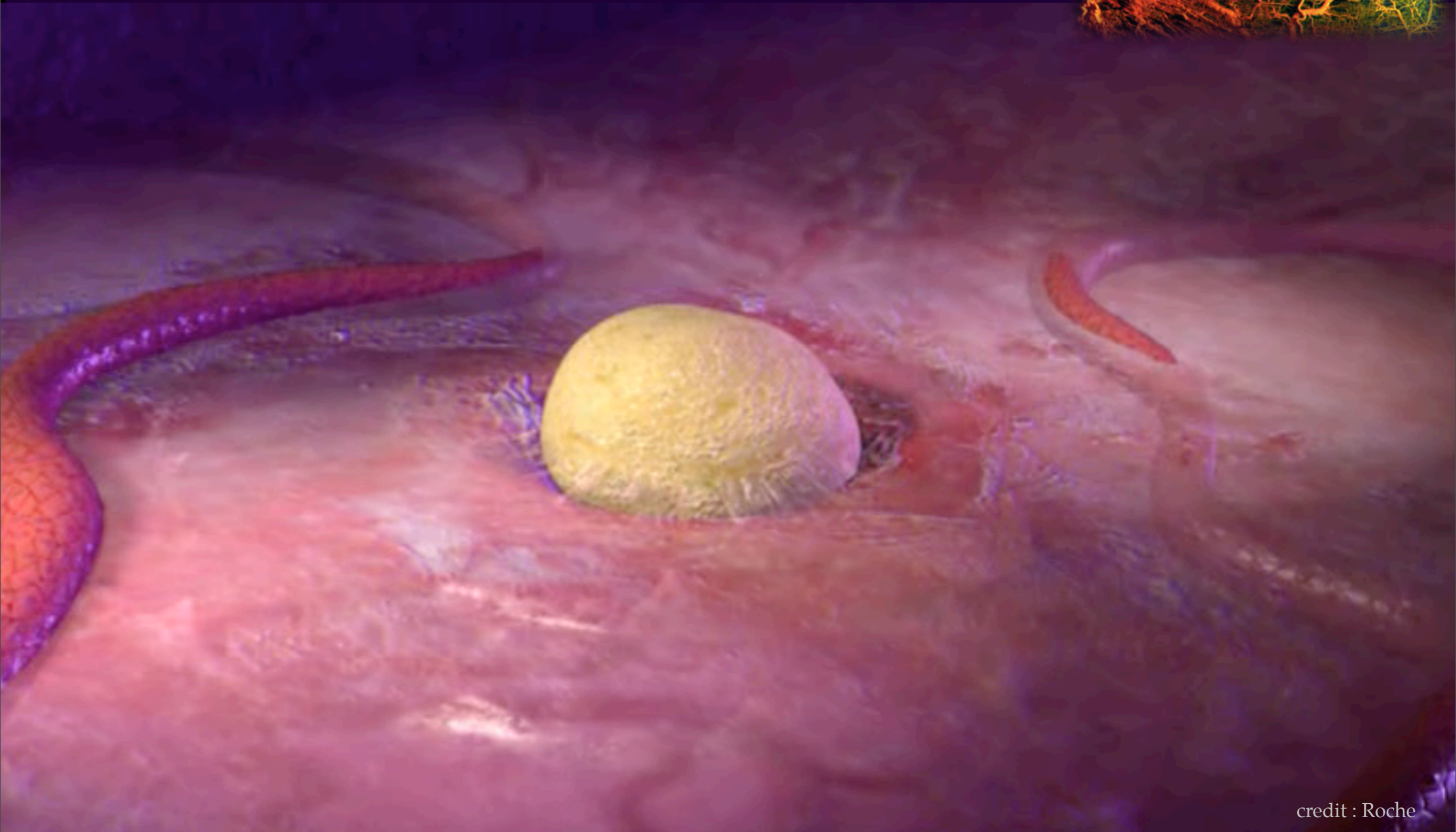
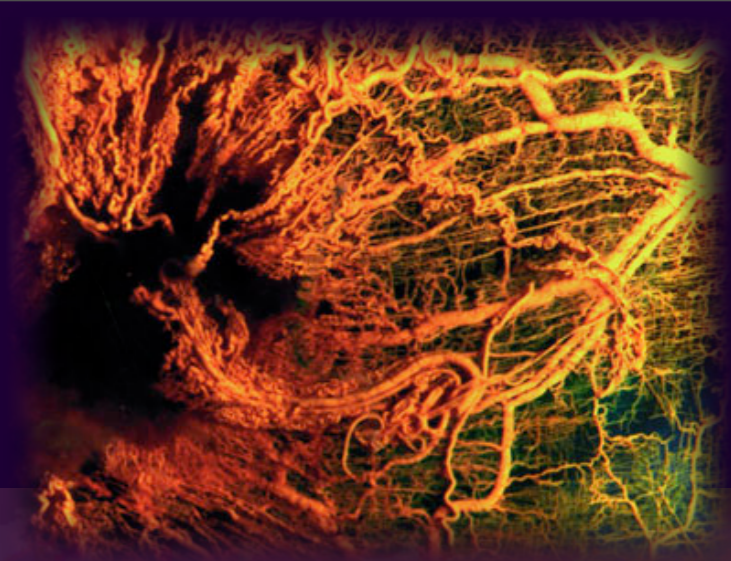
16384 Cores - 10 Billion Particles - 60% efficiency

Runs at IBM Watson Center - BLue Gene/L



Chatelain P., Curioni A., Bergdorf M., Rossinelli D., Andreoni W., Koumoutsakos P., Billion Vortex Particle Direct Numerical Simulations of Aircraft Wakes, Computer Methods in Applied Mech. and Eng. 197/13-16, 1296-1304, 2008

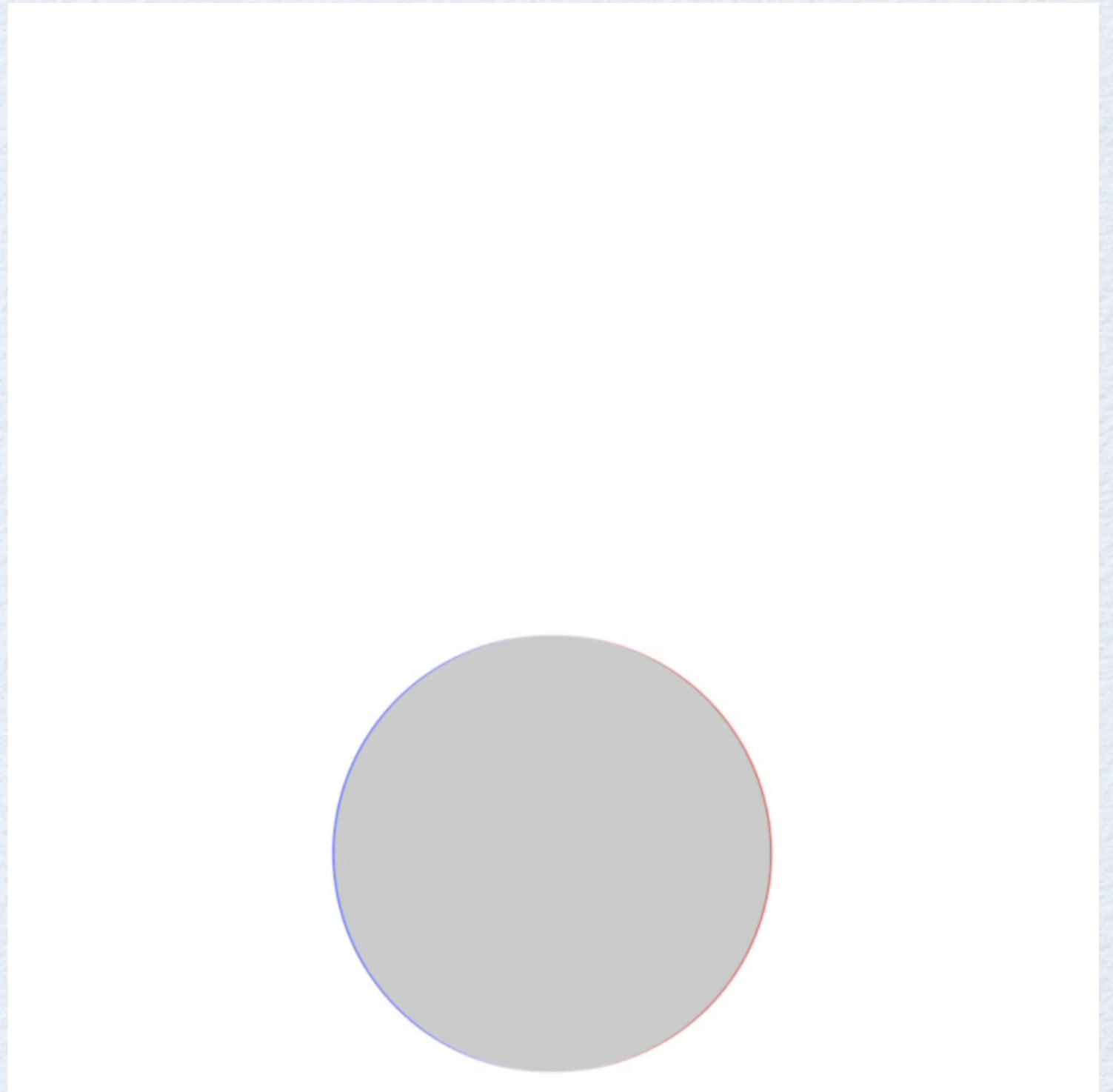
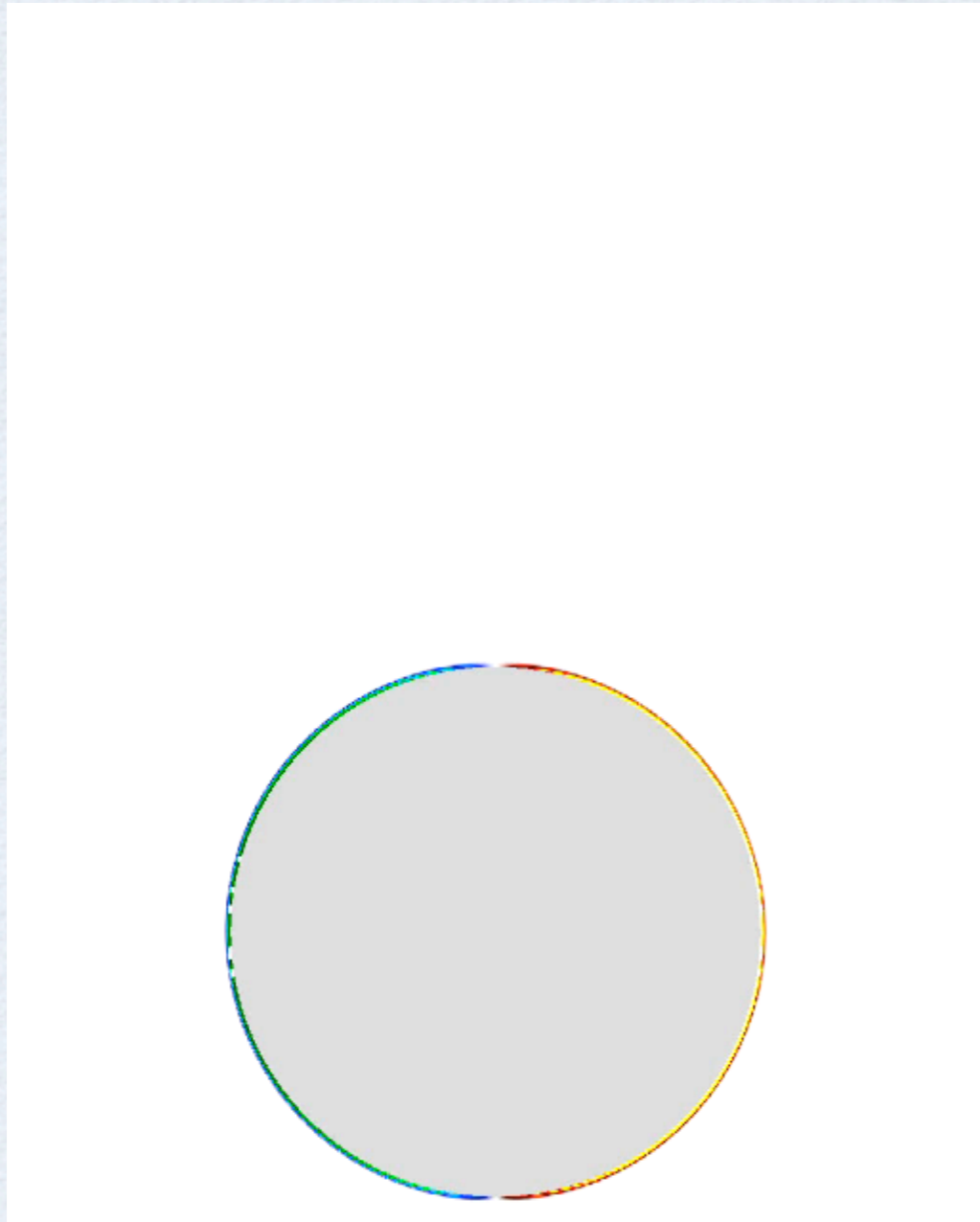
Tumor Induced Angiogenesis



credit : Roche

CFD: Then and Now

Re = 9500 ~ 10⁶ particles



1995 20 Days on CRAY YMP

2009 150sec on GPU

Rossinelli D., et.al., GPU accelerated simulations of bluff body flows using vortex particle methods, **Journal of Computational Physics**, 229, 9, 3316-3333, **2010**

Outline

- **COMPLEX DEFORMING GEOMETRIES**
 - Meshing or Meshless ?
- **FAST AND ACCURATE SIMULATIONS**
 - Multiresolution and GPUs
- **APPLICATIONS**
 - Fish Hydrodynamics
 - Tumor induced Angiogenesis

PARTICLES : Lagrangian, Conservation and Other Laws

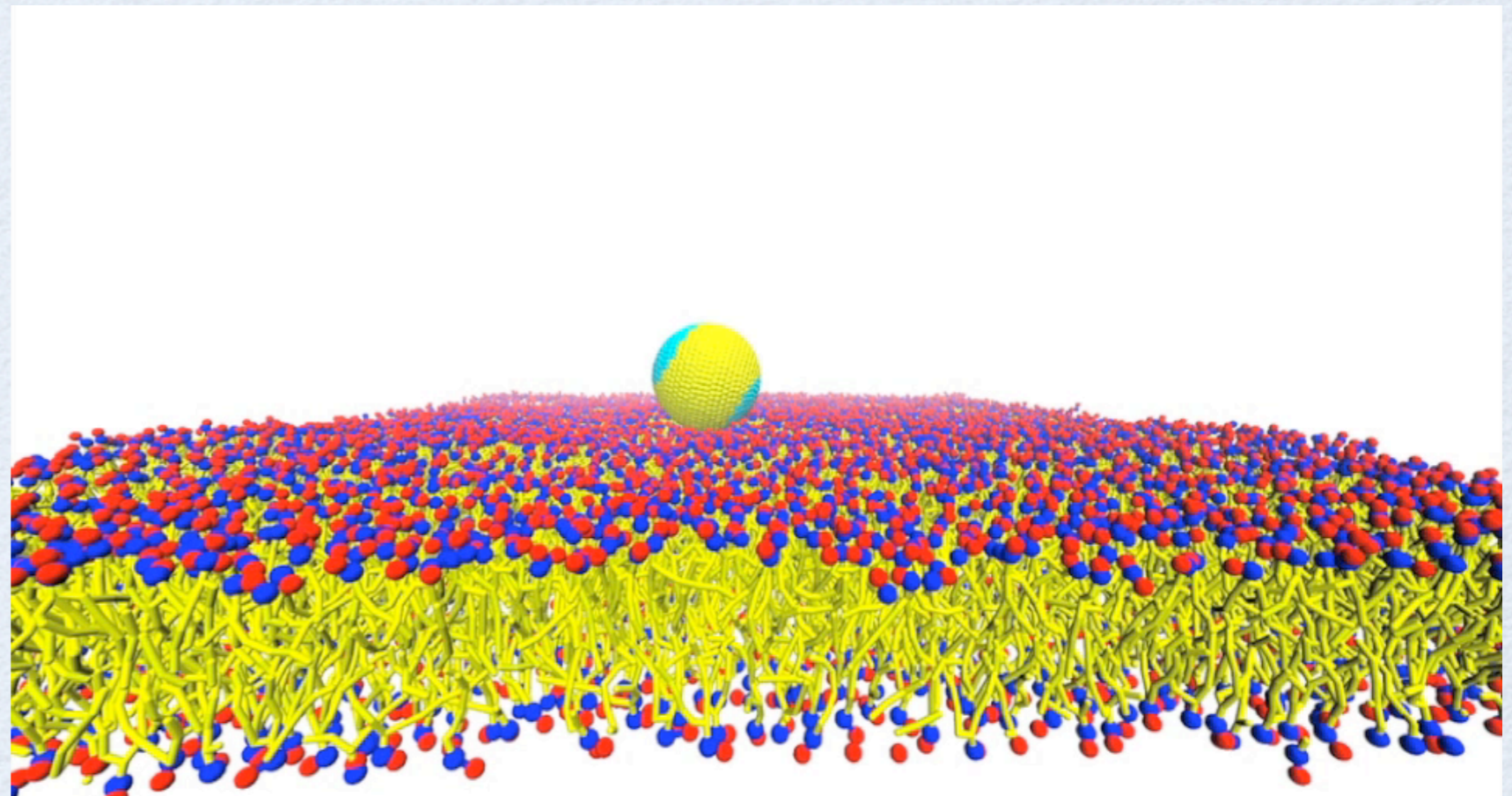
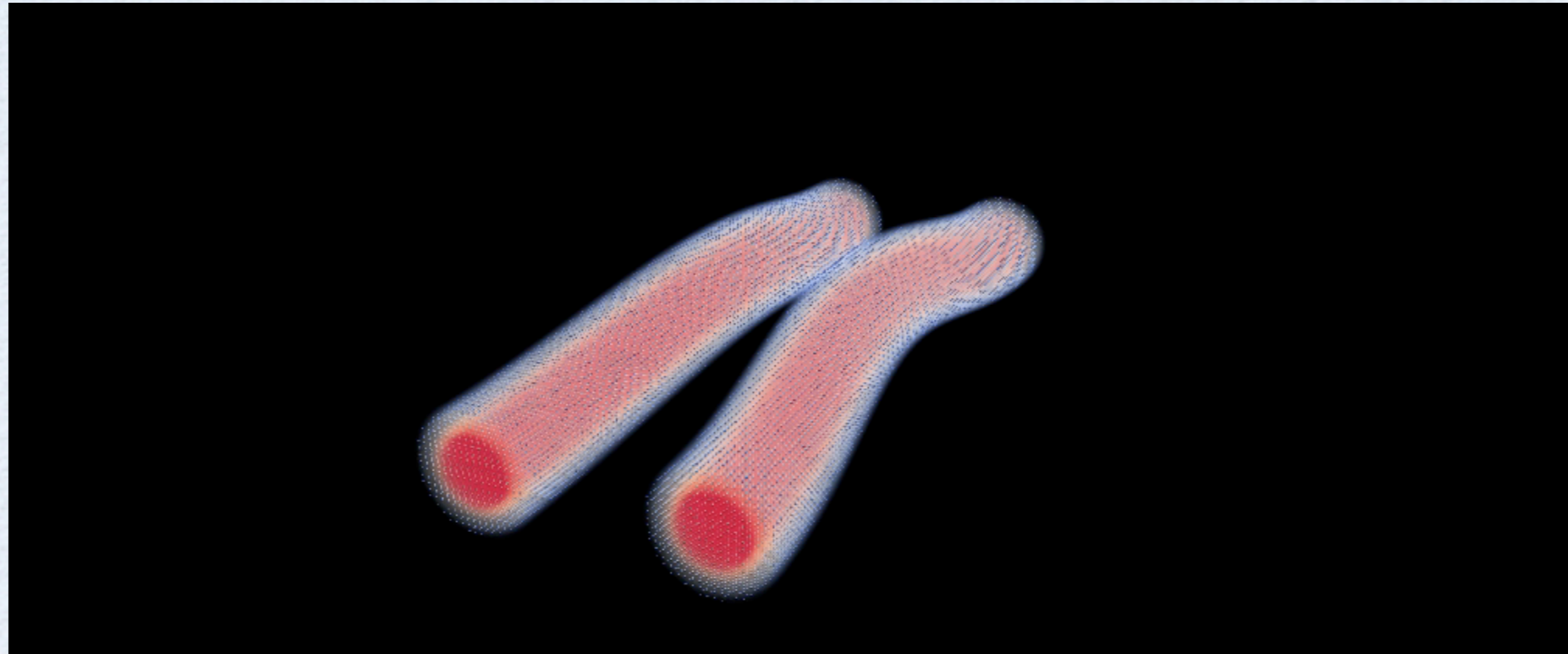
SPH, Vortex Methods

$$\rho_p \frac{D\mathbf{u}_p}{Dt} = (\nabla \cdot \sigma)_p$$

$$\frac{d\mathbf{x}_p}{dt} = \mathbf{u}_p$$

$$m \frac{d\mathbf{u}_p}{dt} = F_p$$

MD, DPD, CGMD



PARTICLE APPROXIMATIONS

Function Mollification

$$\Phi_\epsilon(x) = \int \Phi(y) \zeta_\epsilon(x - y) dy$$

Smooth Particle Quadrature

$$\Phi_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d \Phi_p(t) \zeta_\epsilon(x - x_p(t))$$



are Particles MESH Free ?

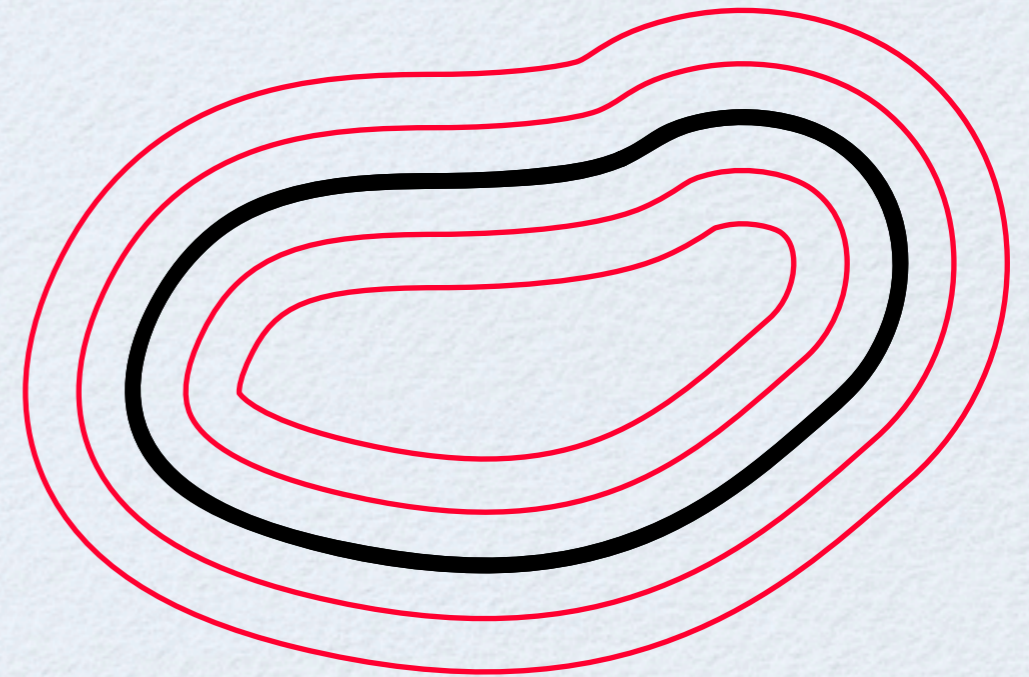
SURFACES -> LEVEL SETS

$$\Gamma(t) = \{ \mathbf{x} \in \Omega \mid \phi(\mathbf{x}, t) = 0 \}$$

$$|\nabla \phi| = 1$$

EVOLVING LEVEL SETS

$$\frac{\partial \Phi}{\partial t} + \mathbf{u} \cdot \nabla \Phi = 0$$

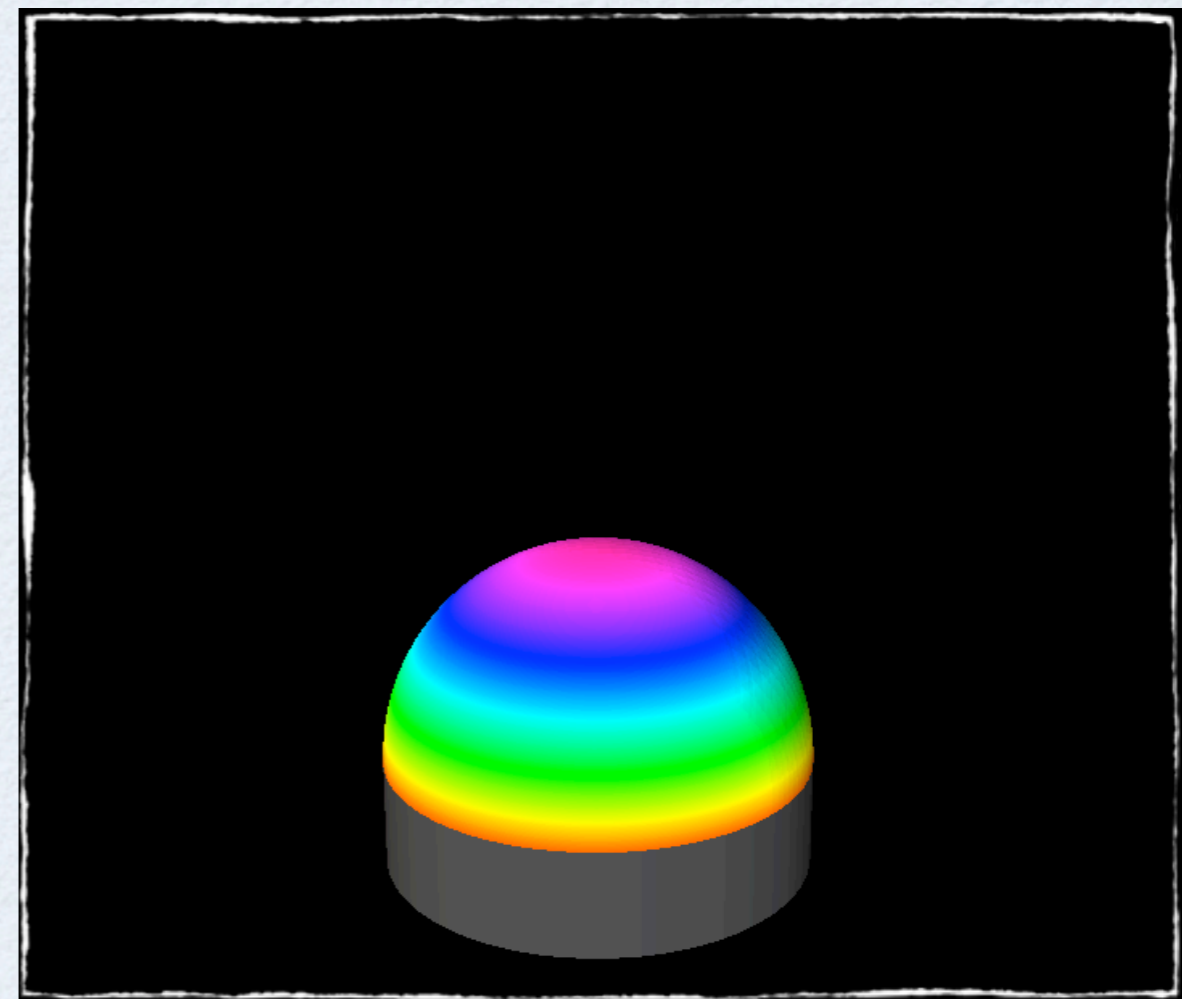


PARTICLES

$$\Phi_\epsilon^h(x, t) = \sum_{p=1}^{N_p} h_p^d \Phi_p(t) \zeta_\epsilon(x - x_p(t))$$

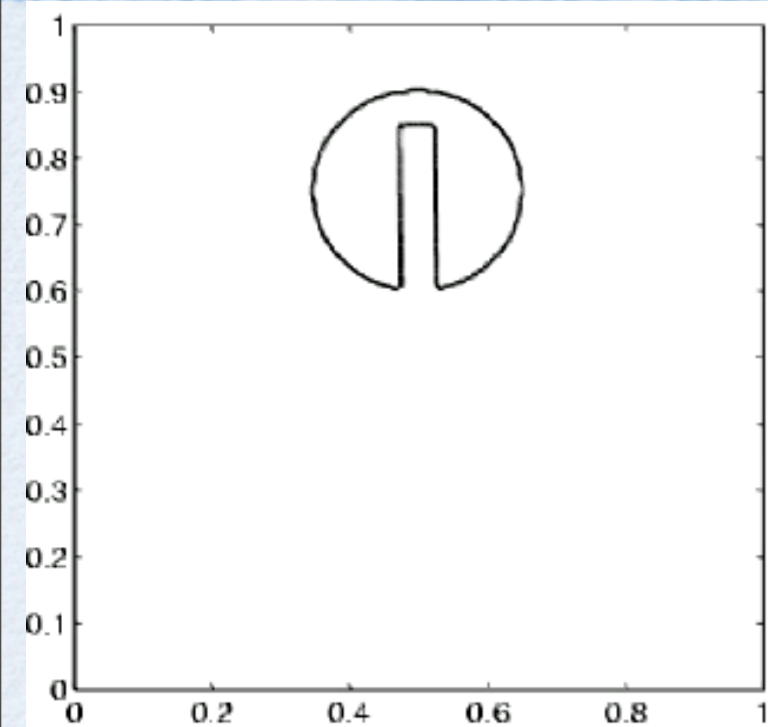
Lagrangian Surface Transport

$$\frac{dx_p}{dt} = \mathbf{u}_p \quad \frac{D\Phi_p}{Dt} = 0$$



S. E. Hieber and P. Koumoutsakos. A Lagrangian particle level set method. **J. Computational Physics**, 210:342-367, 2005

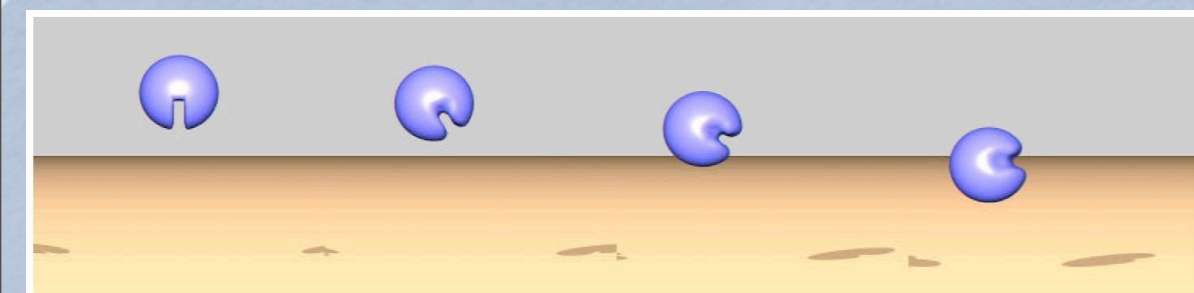
Lagrangian vs Eulerian Descriptions



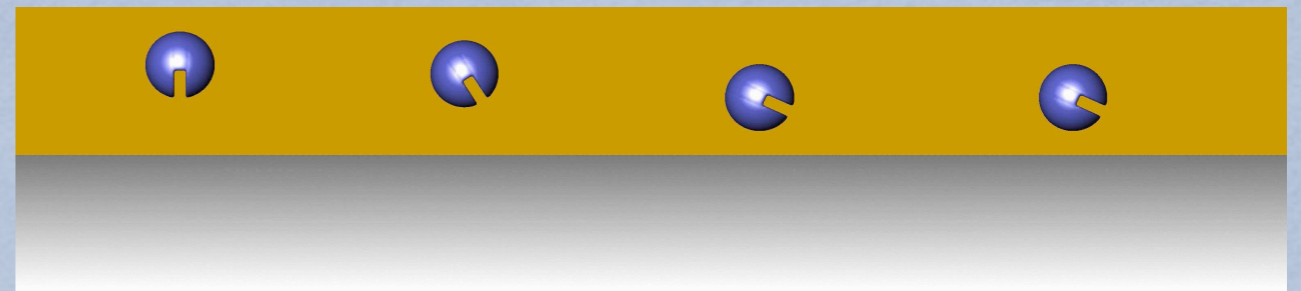
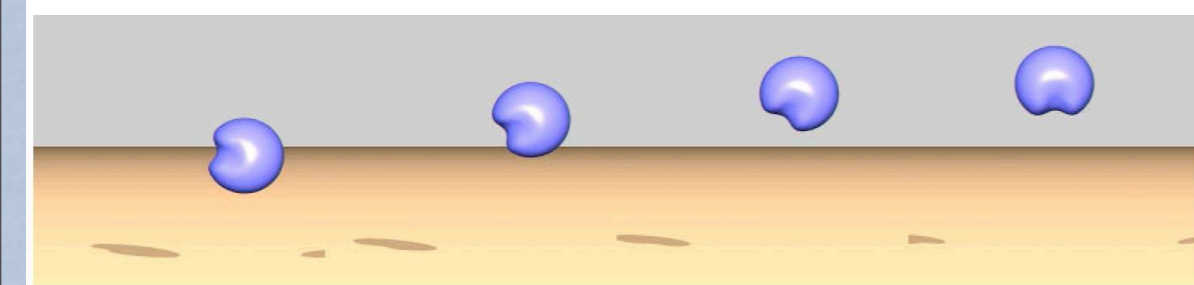
- **PARTICLE LEVEL SETS** exact for rigid body motion

$$\Phi(\mathbf{x}, t) = \Phi_0(\mathbf{x} - \mathbf{u}t)$$

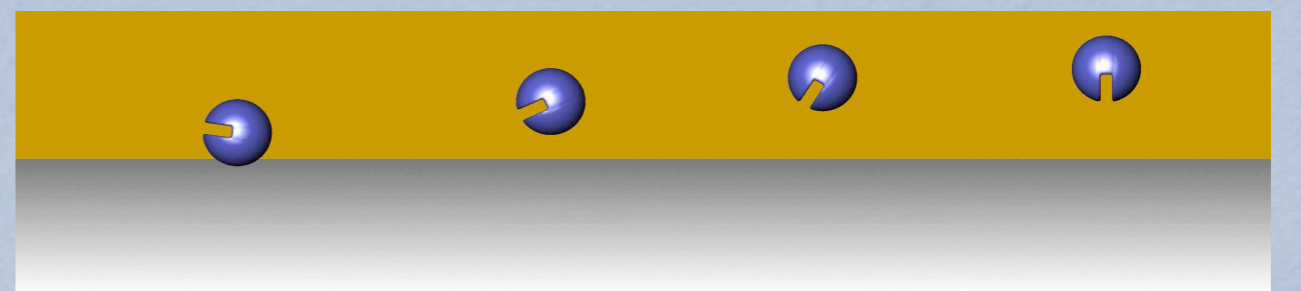
Particle methods **PERFECT**
for **linear** advection



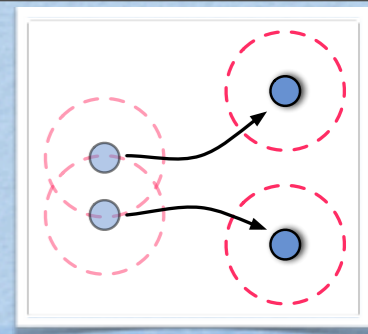
Hybrid Particle-Grid Level Sets
(Enright and Fedkiw, 2002)



Lagrangian Particle Level Sets
(Hieber and Koumoutsakos, 2005)



LAGRANGIAN DISTORTION



- loss of **overlap** -> loss of **convergence**

Particles follow flow trajectories - **Location distortion**

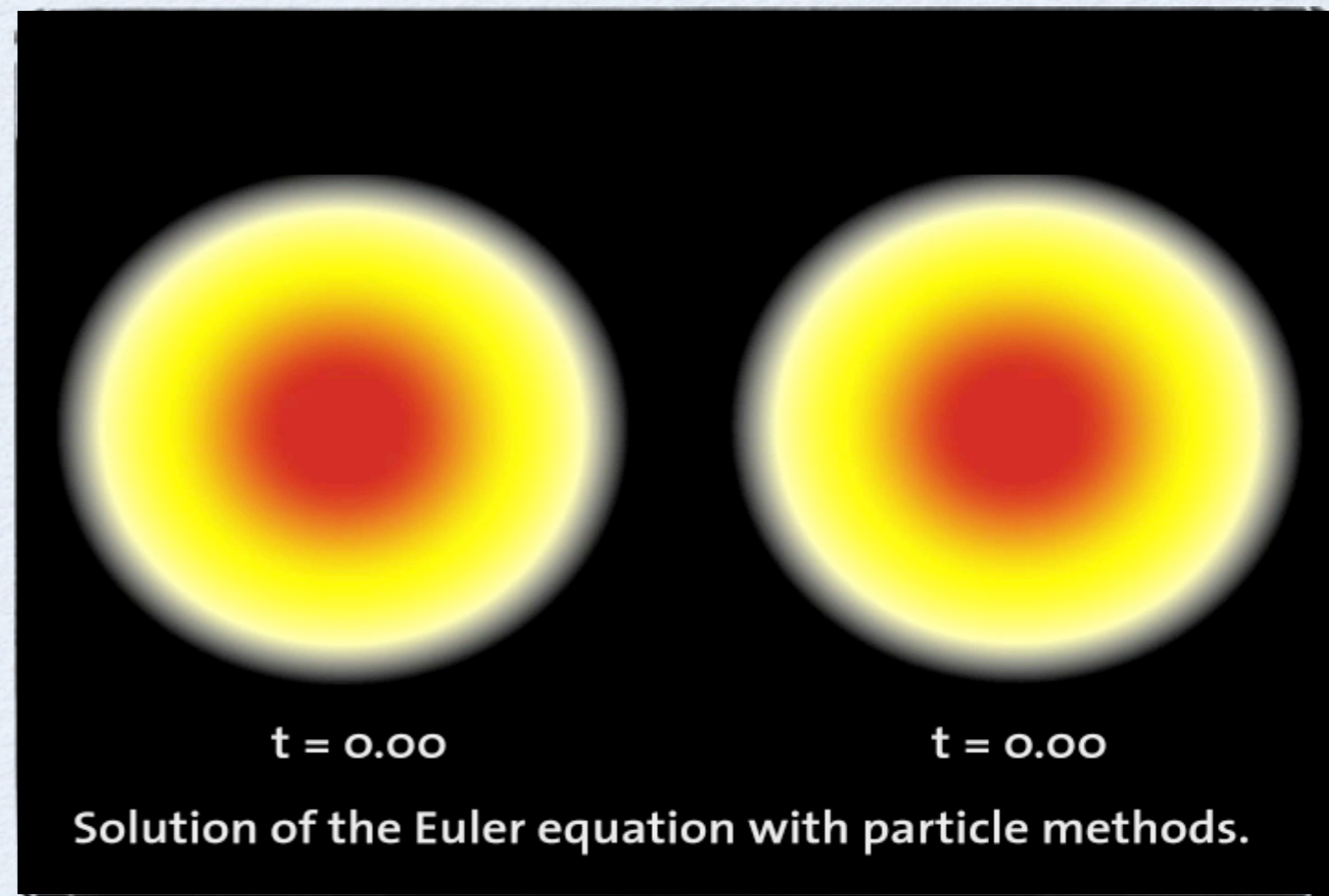
EXAMPLE :

Incompressible 2D Euler Equations

$$\omega = \nabla \times \mathbf{u} \quad \nabla \cdot \mathbf{u} = 0$$

$$\frac{D\omega}{Dt} = 0$$

There is an **exact** axisymmetric solution



Are Particle Methods Grid Free ?

How to fix it ?

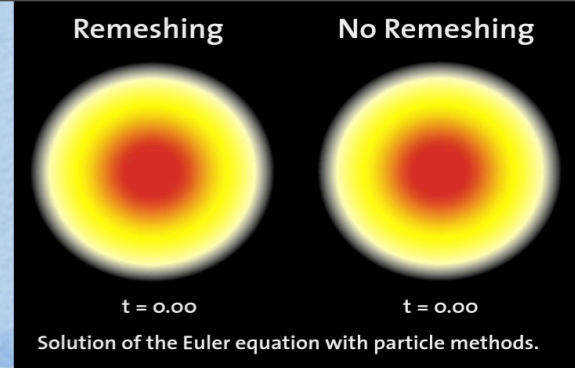
- Modify the smoothing kernels (SPH - Monaghan)
- Re-distribute particles with Voronoi Meshes (ALE - Russo)
- Re-initialise particle strengths (WRKPM - Liu, Belytchko)

DOES NOT WORK
EXPENSIVE - UNSTABLE
EXPENSIVE

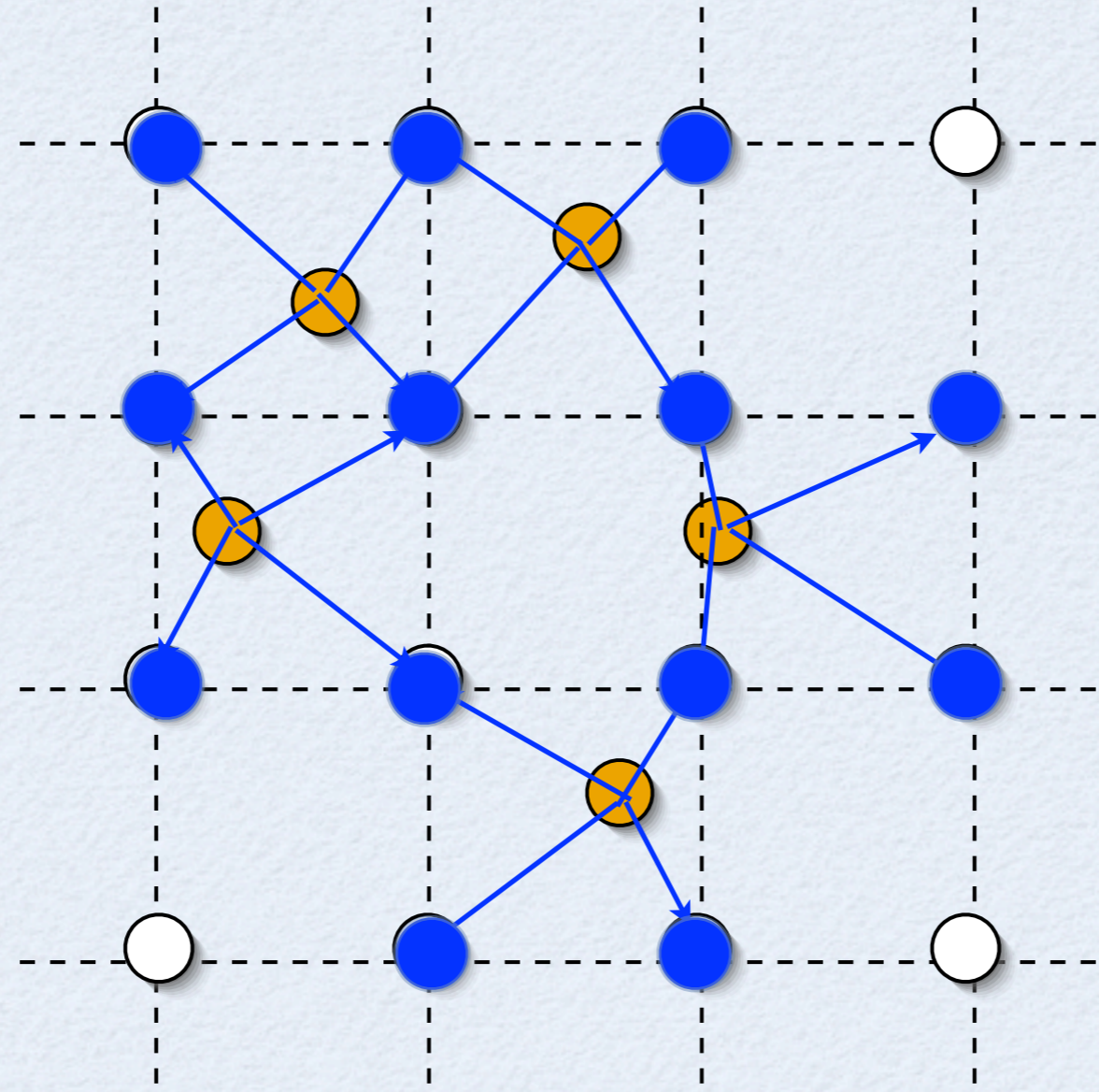
REMESHING : Re-project particles on a mesh

- NO MESH-FREE particle methods
- Can use all the “tricks” of mesh based methods
- High CFL
- Multiresolution & Multiscaling
-

Particle Remeshing



Koumoutsakos, J. Comp. Phys., 1997



Moment Conserving Interpolation : $Q_p^{\text{new}} = \sum_{p'} Q_{p'} M(j h - x_{p'})$

remeshed PARTICLE METHODS (rPM)

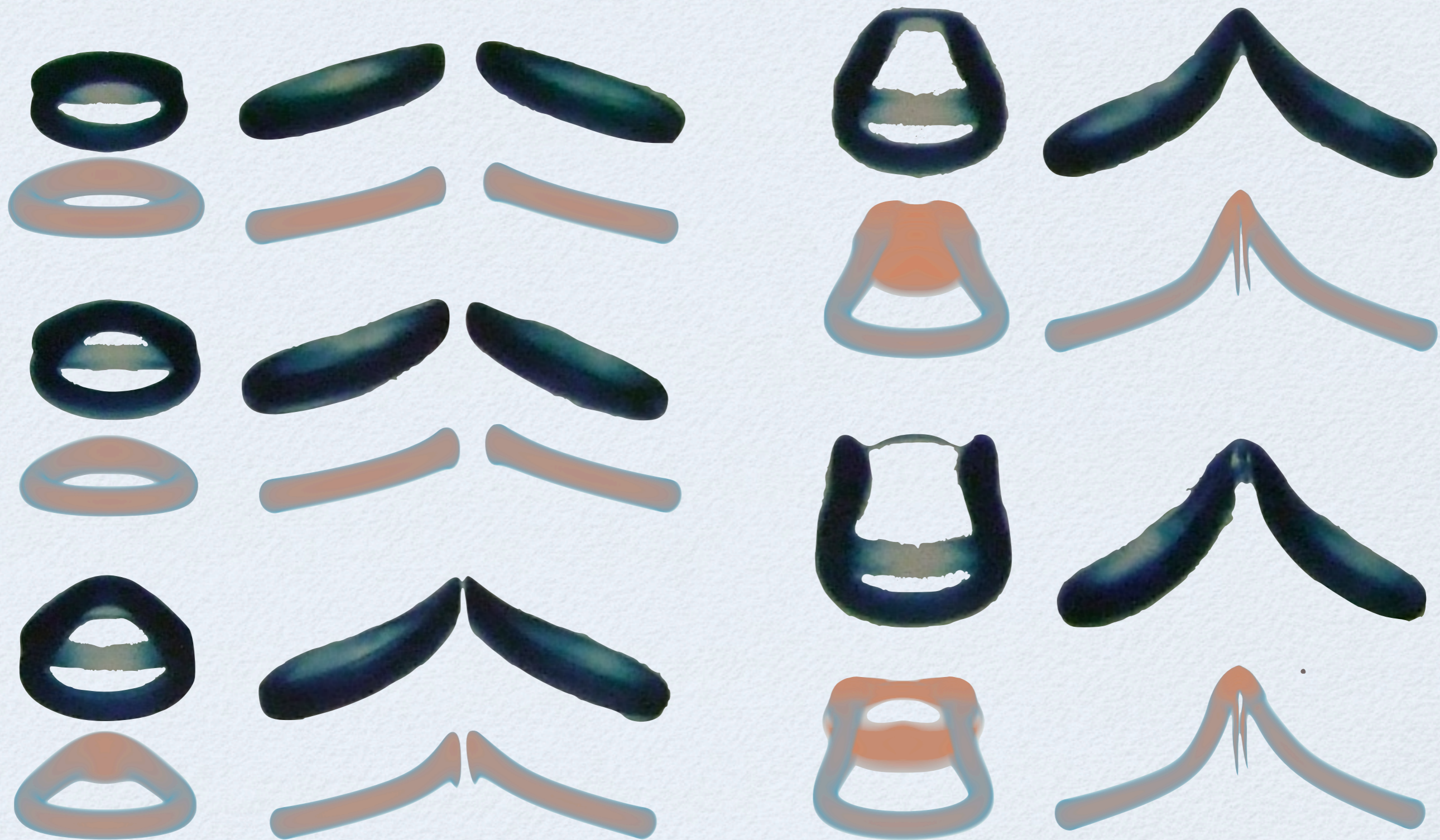
1. ADVECT : Particles -> Large CFL

2. REMESH : Particles to Mesh -> Gather/Scatter

3. SOLVE : Poisson/Derivatives on Mesh -> FFTw/Ghosts

4. RESAMPLE : Mesh Nodes BECOME Particles

VORTEX RING COLLISION, $Re = 1800$



Experiments : P. Schatzle & D. Coles (1986)

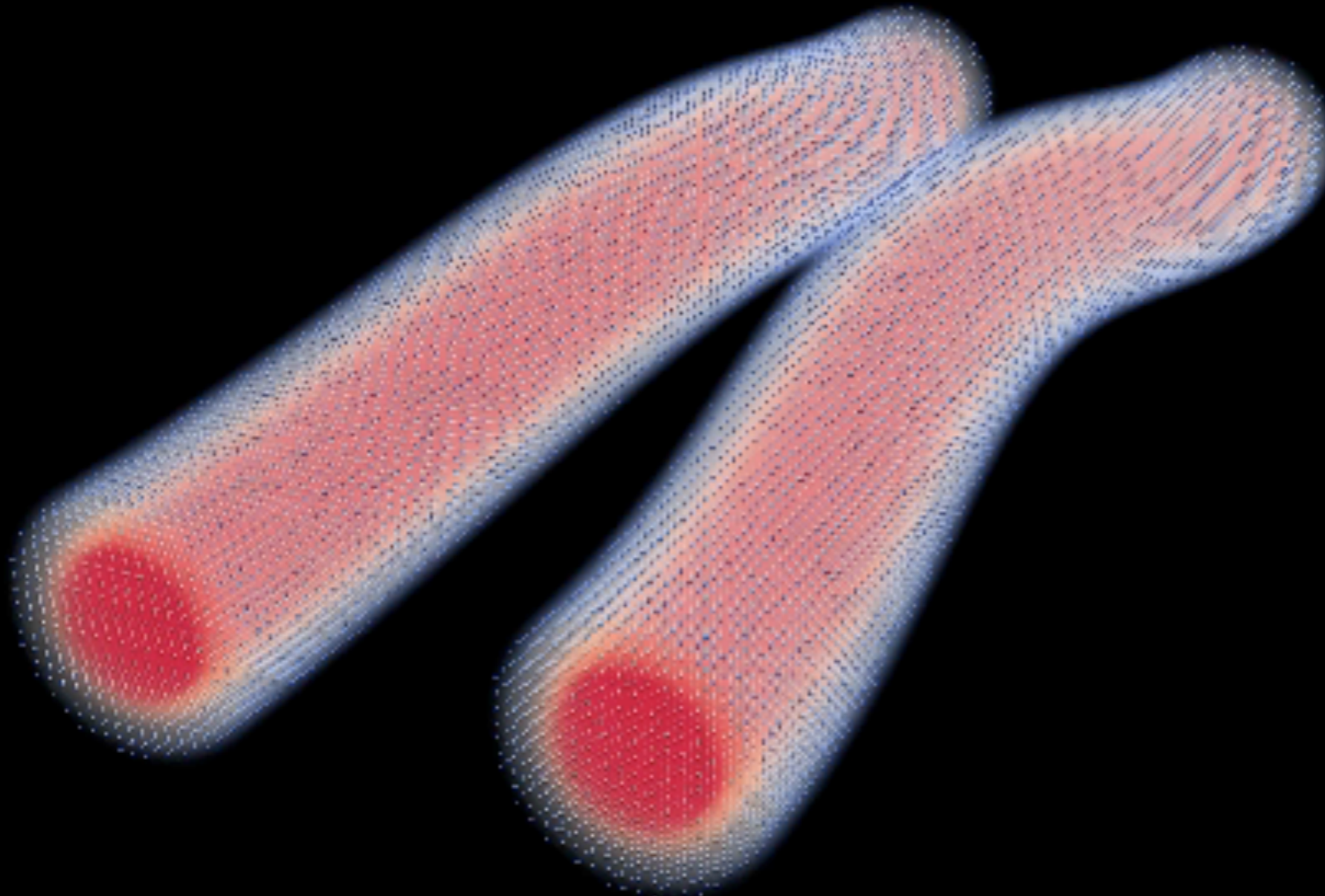
VORTEX DYNAMICS at High Re

van Rees W.M., Leonard A., Pullin D.I.,
Koumoutsakos P., A comparison of vortex and
pseudo-spectral methods for the simulation of
periodic vortical flows at high Reynolds
numbers, **J. of Comp.Physics**, 2011

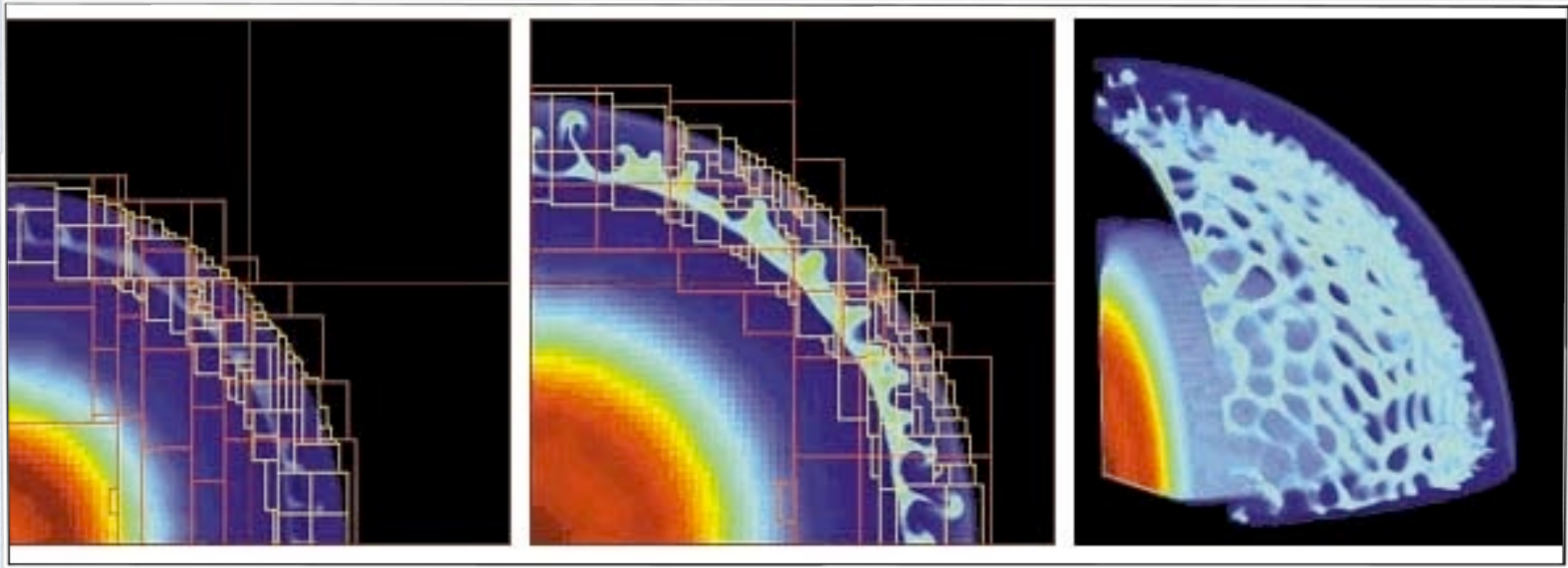


rPM : ADAPTIVE

yet inefficient !



Adaptive Mesh Refinement



- Support of unstructured grids
- Different mesh orientations
- Low compression rate (Gradient, curvature)
- No explicit control on the compression error

Berger, Colella, J. Comp. Phys., 1989

Wavelet Compression



50:1

WAVELET PARTICLE METHOD

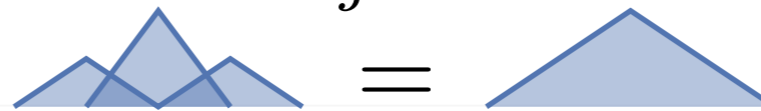
While particles are on grid locations

mollification kernel \longleftrightarrow basis/scaling function

Multiresolution analysis (MRA) $\{\mathcal{V}^l\}_{l=0}^L$ of particle quantities

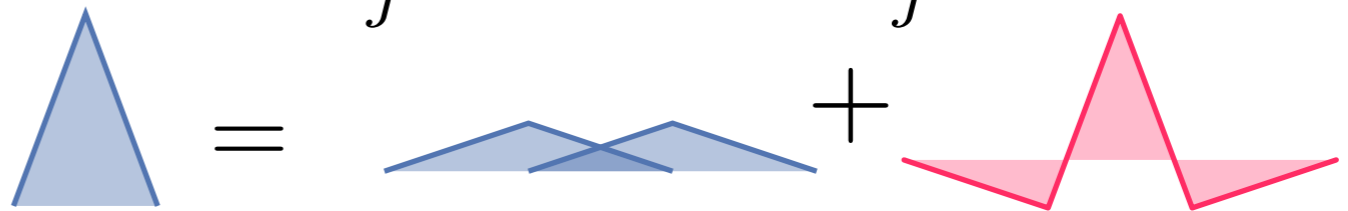
Refineable kernels
as basis functions of \mathcal{V}^l

$$\zeta_k^l = \sum_j h_{j,k}^l \zeta_j^{l+1}$$



Wavelets as basis functions of the
complements \mathcal{W}^l

$$\zeta_k^{l+1} = \sum_j \tilde{h}_{j,k}^l \zeta_j^l + \sum_j \tilde{g}_{j,k}^l \psi_j^l$$



PARTICLETS : REMESHED PARTICLES + WAVELETS

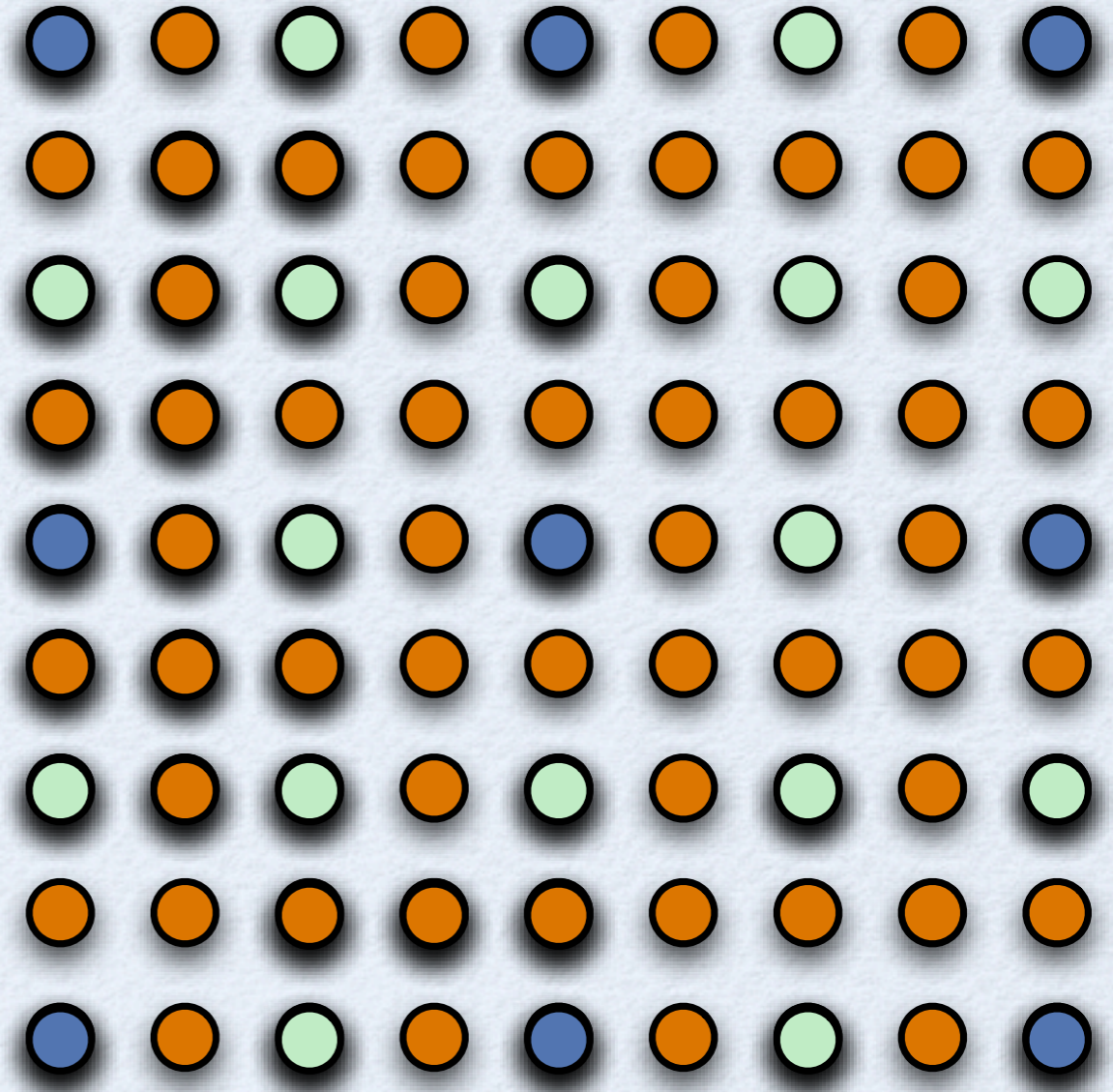
M. Bergdorf, P. Koumoutsakos. A Lagrangian Particle-Wavelet Method, Multiscale Modeling and Simulation: A SIAM Interdisciplinary Journal, 5(3), 980-995, 2006

$$q^L = \sum_k c_k^0 \zeta_k^0 + \sum_{l < L} \sum_k d_k^l \psi_k^l$$

“ground” level \nearrow c_k^0 ζ_k^0 \nearrow d_k^l ψ_k^l
detail coefficients \nearrow wavelets

Wavelet Active Points
=
Active Grid Points

1. Remesh
2. Wavelets - Compress/Adapt
3. Convect
4. Wavelets Reconstruct
5. GOTO 1



Wavelet-adapted grids

PDE:

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0$$

Spatial Differences = filtering operations:

$$F(c_k^l) = \sum_{j=s_f}^{e_f-1} c_{k+j}^l \beta_j^l, \quad \beta_j^l \text{ function of } \{c_m^l\}$$

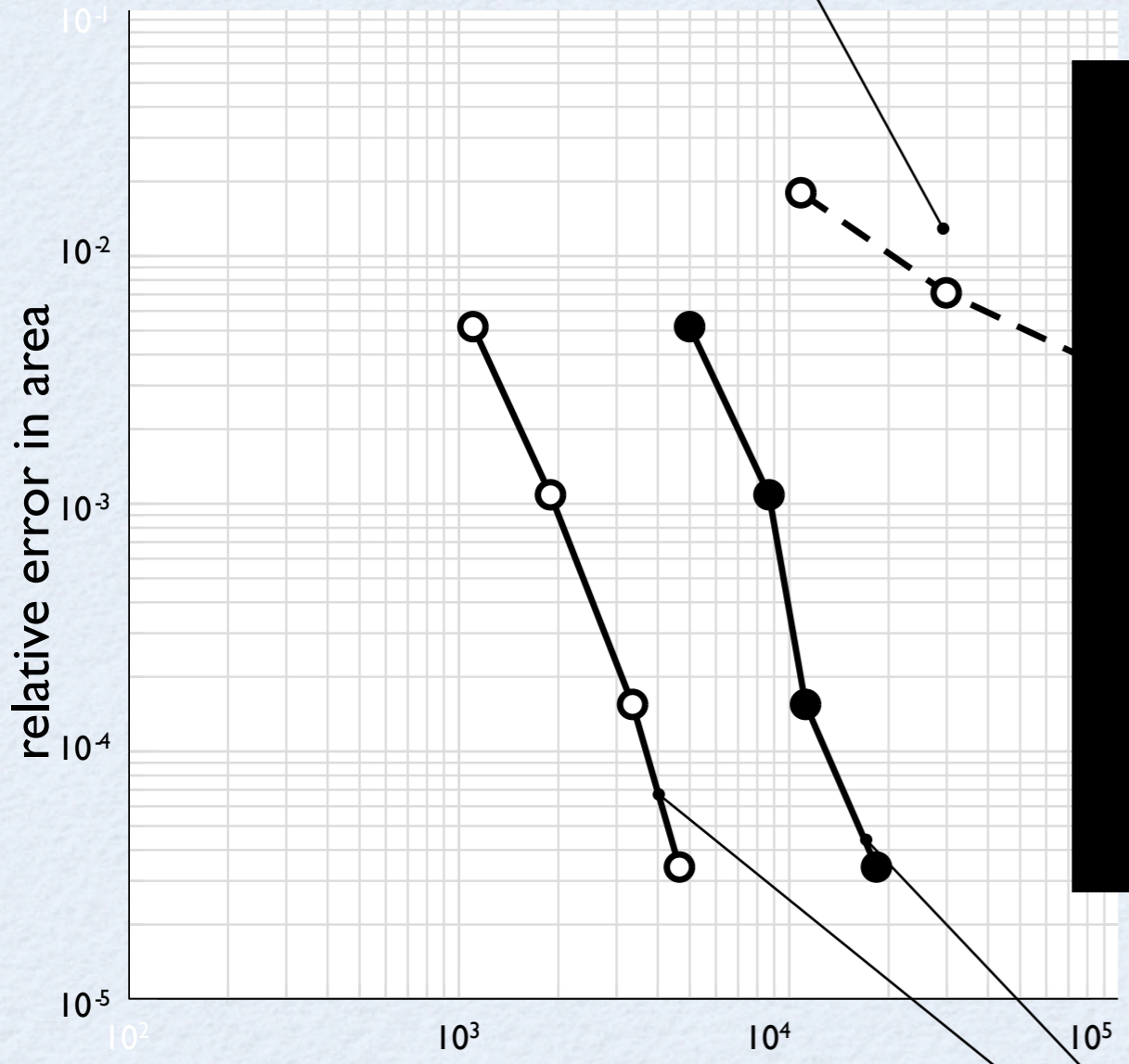
GHOSTS : **easy to compute** – (locally) uniform filtering of the grid

MULTIRESOLUTION LEVEL SETS

M. Bergdorf, P. Koumoutsakos. A Lagrangian Particle-Wavelet Method, Multiscale Modeling and Simulation: A SIAM Interdisciplinary Journal, 5(3), 980-995, 2006

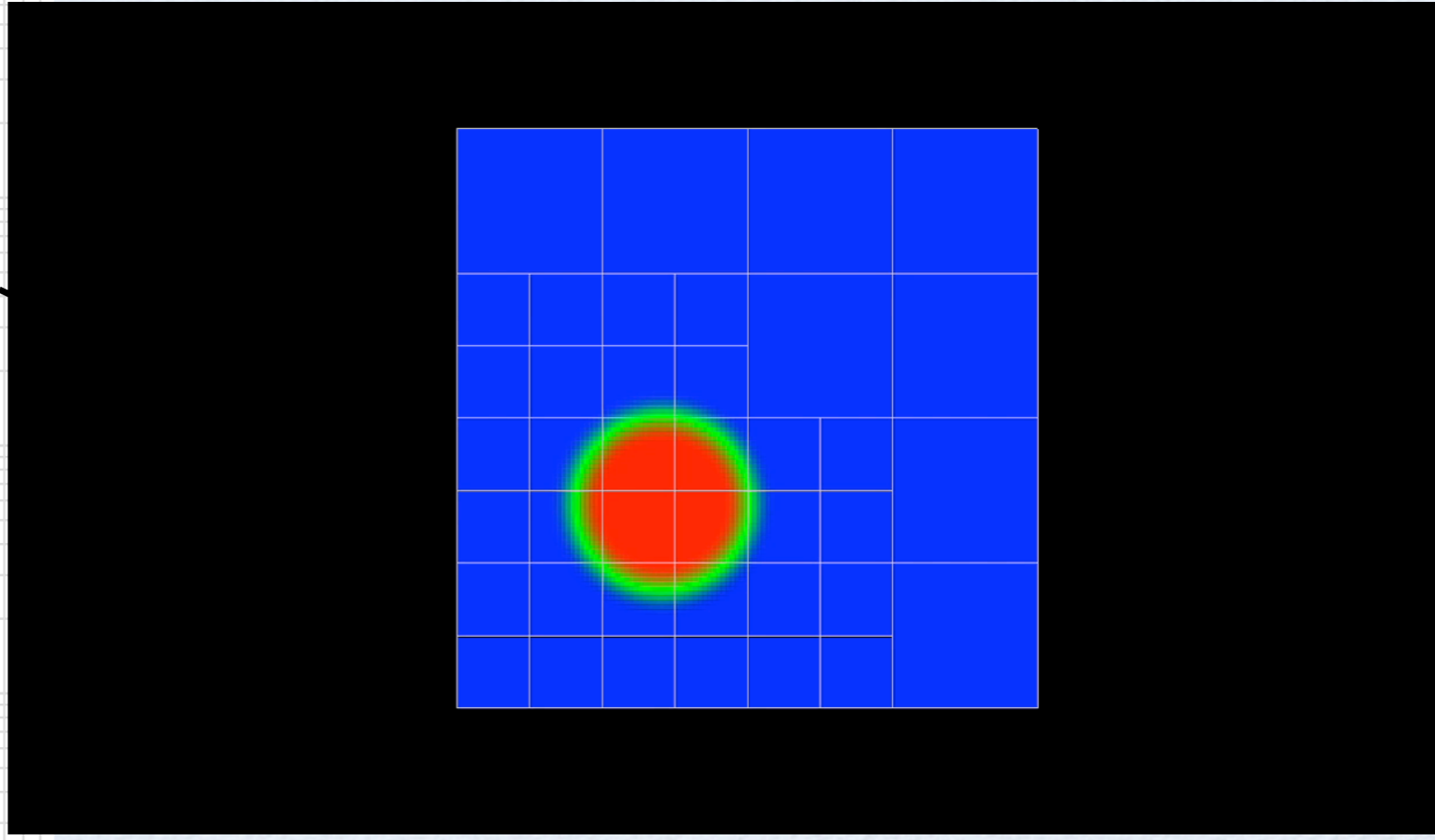
Enright, Fedkiw et al, 2002

dof = # grid points + aux. particles at t=0.0



degrees of freedom

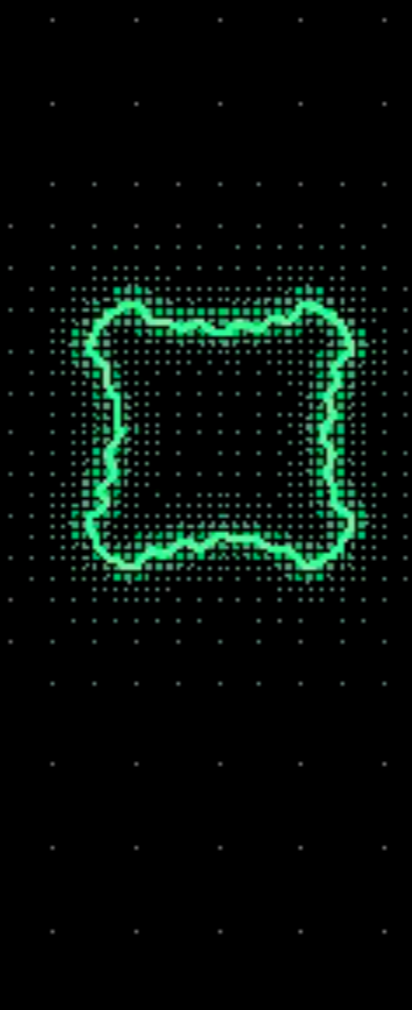
$CFL_{max} \sim 40$



Present Method

dof = # active gp/particles at t=0.0

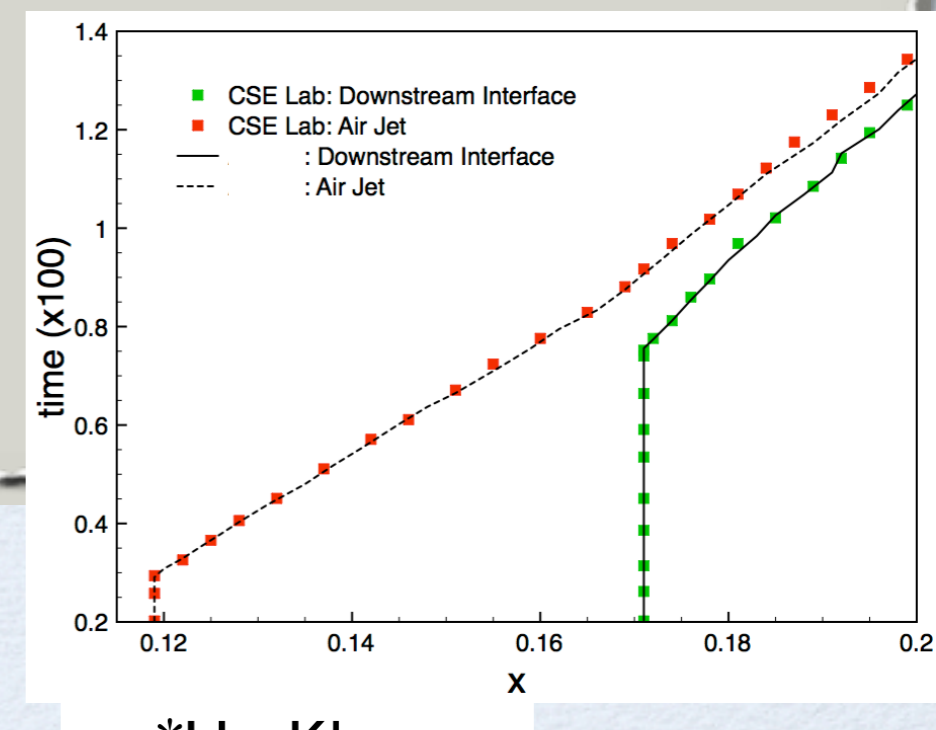
dof = # active gp/particles at final time



Shock Bubble Interaction

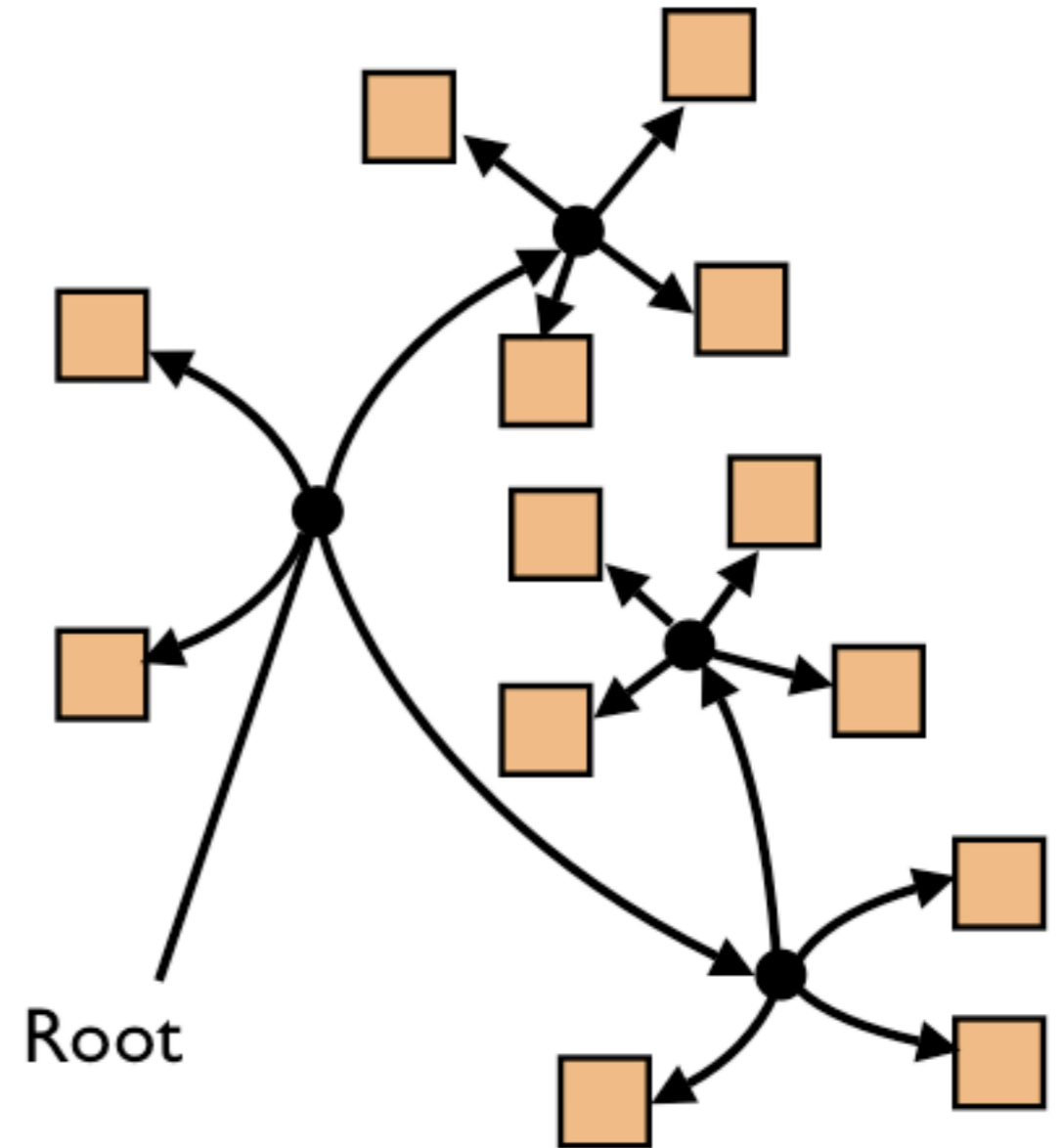
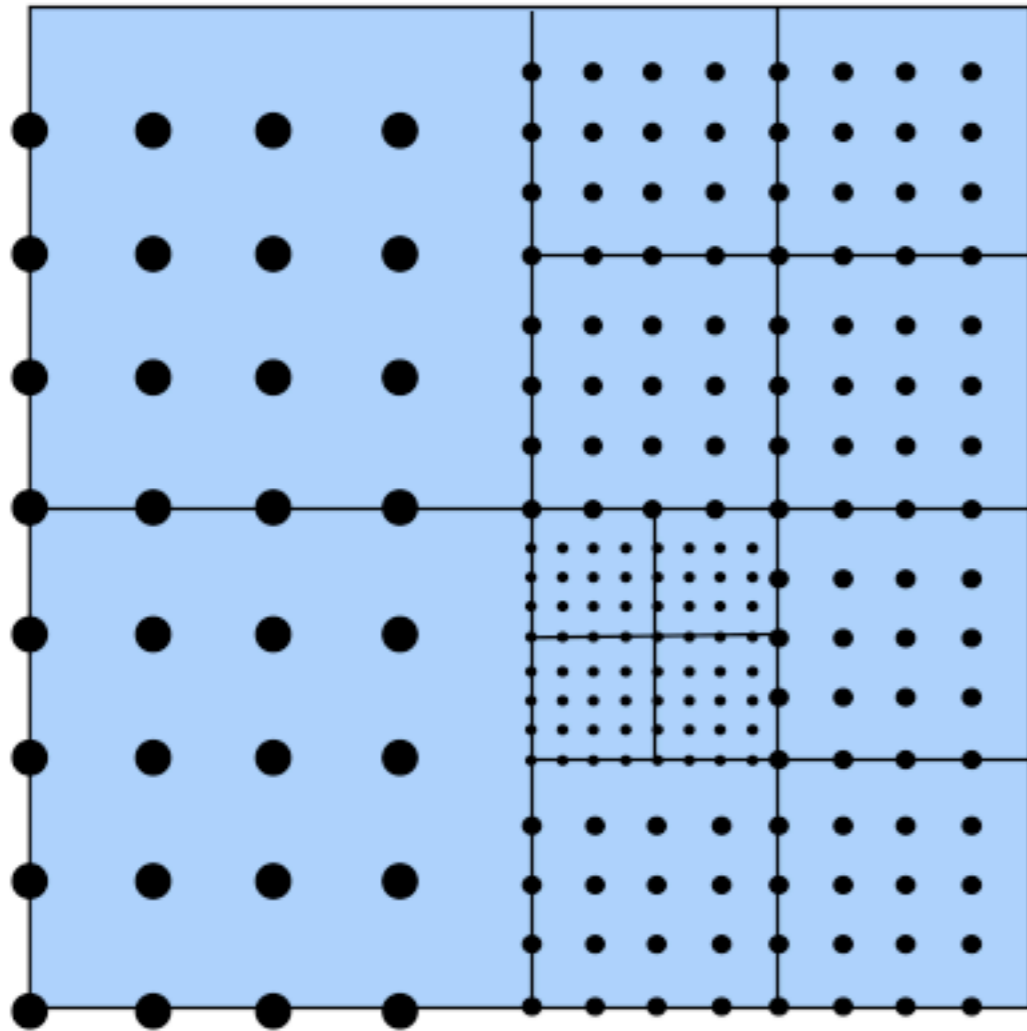
($M=3$, $At=0.8$)

FINEST RESOLUTION EQUIVALENT
8000 x 8000 uniform grid
~40 times smaller adaptive



Hejazialhosseini B., Rossinelli D., Bergdorf M., Koumoutsakos P.,
High order Finite Volume methods on Wavelet-adapted Grids with
Local Time-Stepping on Multicore Architectures for the Simulation
of Shock-Bubble Interactions, **J. of Comp. Physics**, 2010

Block Grid for Multi/Many-core:



- Neighbors look-up: less memory indirections
- Less #ghosts
- Within a block: random access

Multiresolution + MultiCore + GPU

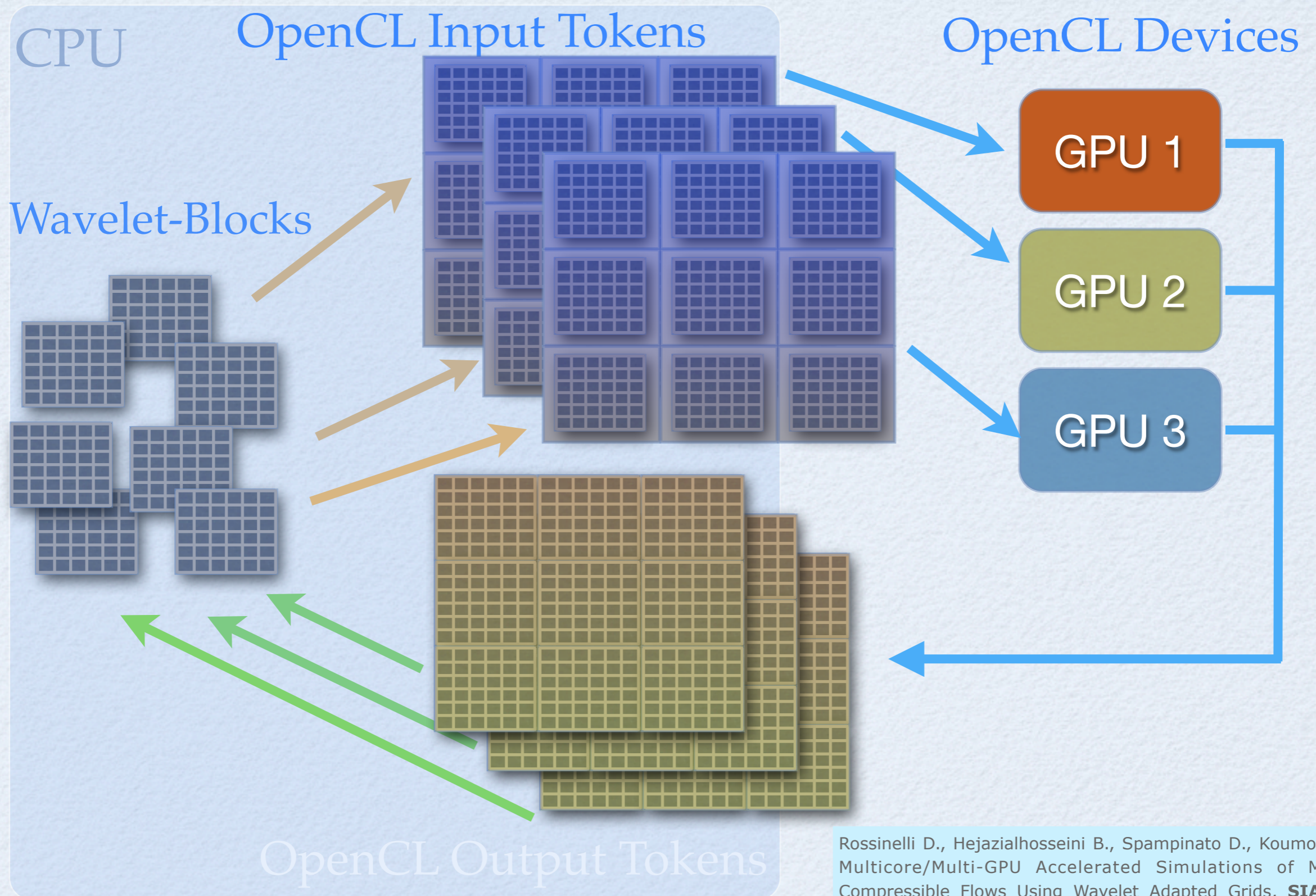
- MULTIPLE TASKS

1. task parallel, ghost computing -> **multi-core**
2. fine-grained data parallelism for RHS -> **GPUs**
3. Integration step -> **multi-core**

$$q^{\text{new}} = q^{\text{old}} + \delta t \underbrace{\mathbf{F}(q^{\text{old}}, \nabla q^{\text{old}})}_{\text{CUDA/OpenCL}}$$

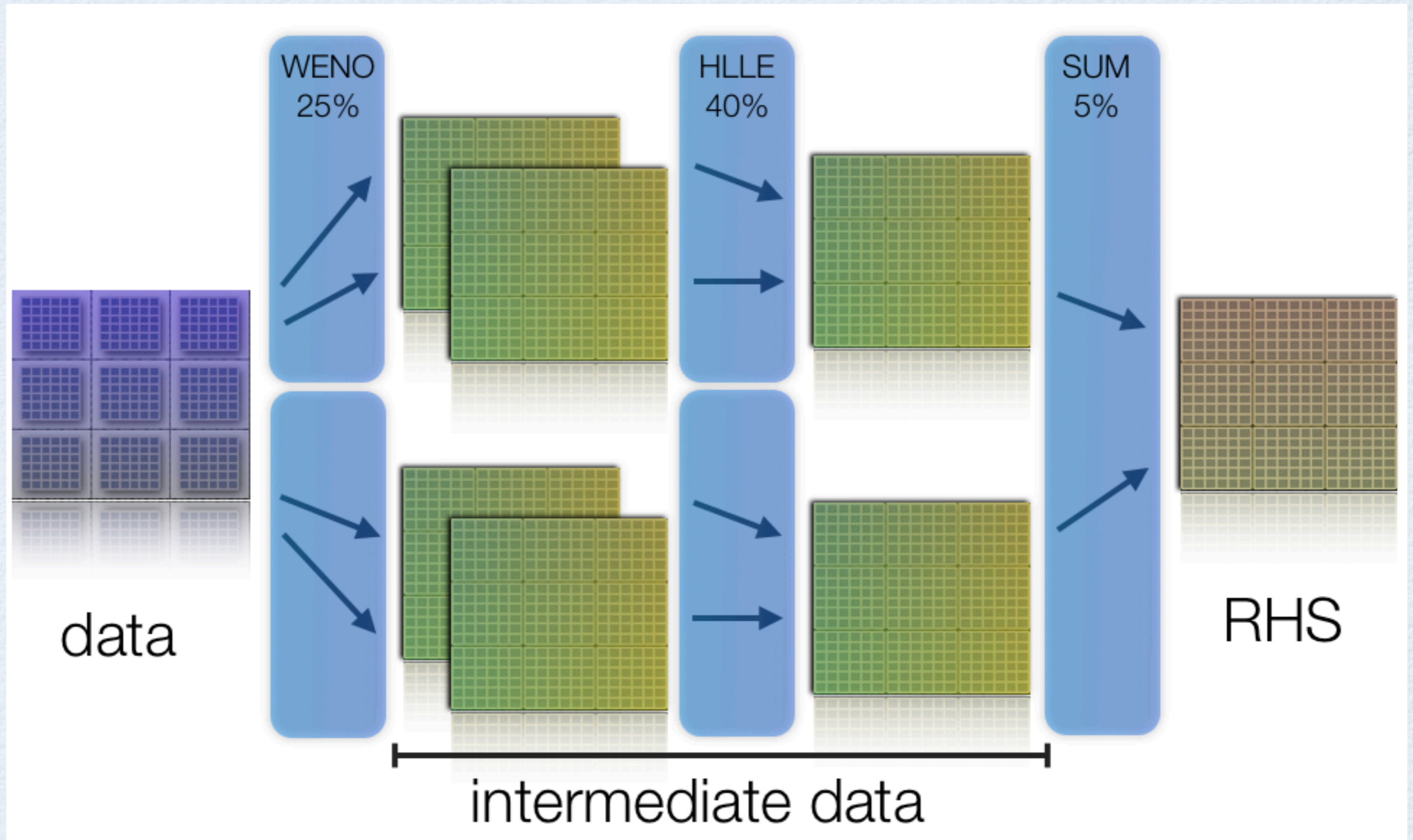
- How much *faster* than CPU-only execution?
- How much *different* are CPU/GPU and CPU-only solutions?

Wavelet Blocks on GPUs



Rossinelli D., Hejazialhosseini B., Spampinato D., Koumoutsakos P., Multicore/Multi-GPU Accelerated Simulations of Multiphase Compressible Flows Using Wavelet Adapted Grids, **SIAM J. Sci. Comput.**, 33, pp. 512-540, 2011

Multiple kernels for the GPU

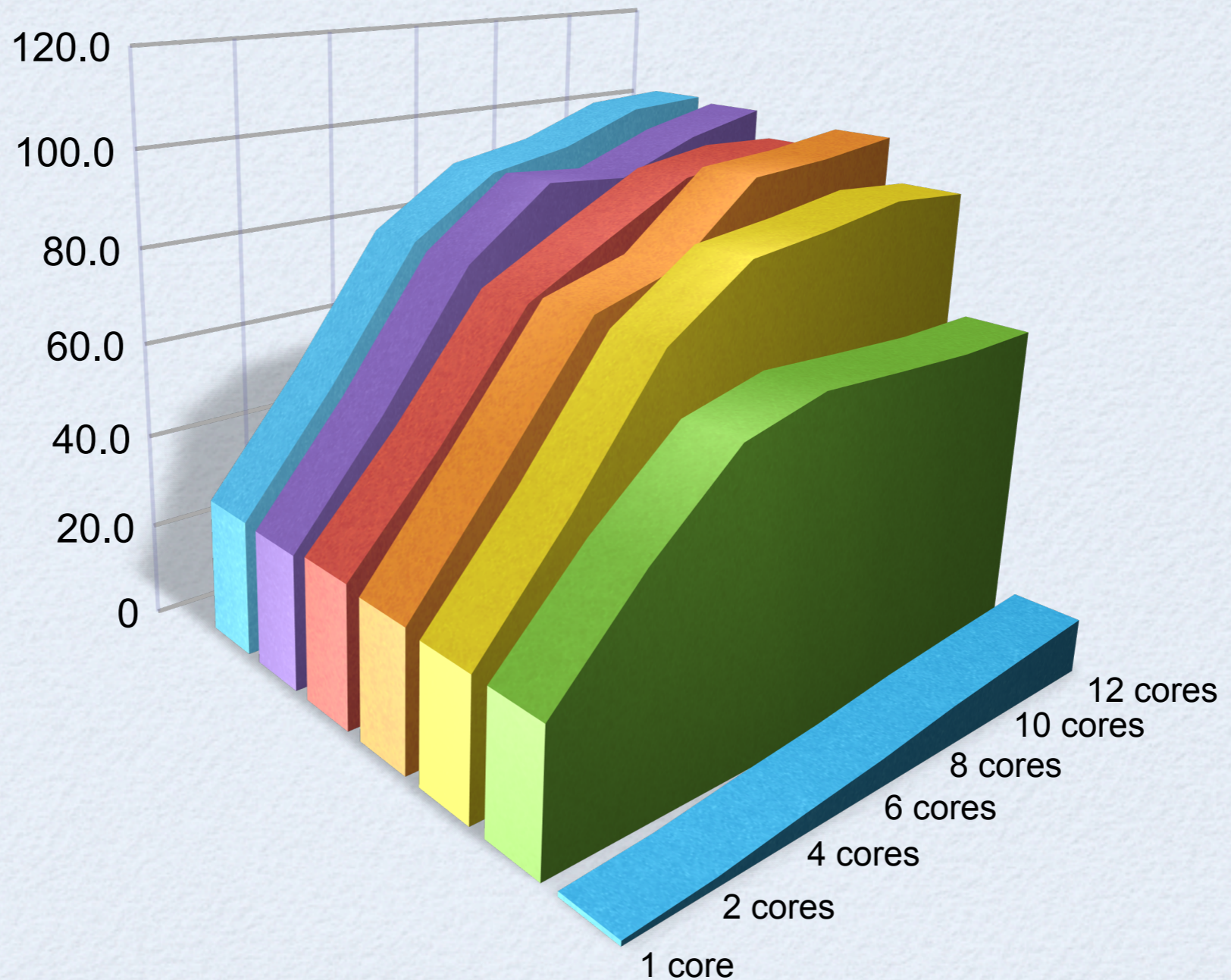


Performance I : Strong Scaling

Strong scaling (effective 8000^2 - actual 40x less) vs. #GPUs, #CPU cores

Speedup over 1 core/0 GPU

- 0 GPUs
- 1 GPU
- 2 GPUs
- 3 GPUs
- 4 GPUs
- 5 GPUs
- 6 GPUs



No Local Time Stepping

Performance II : Time to Solution

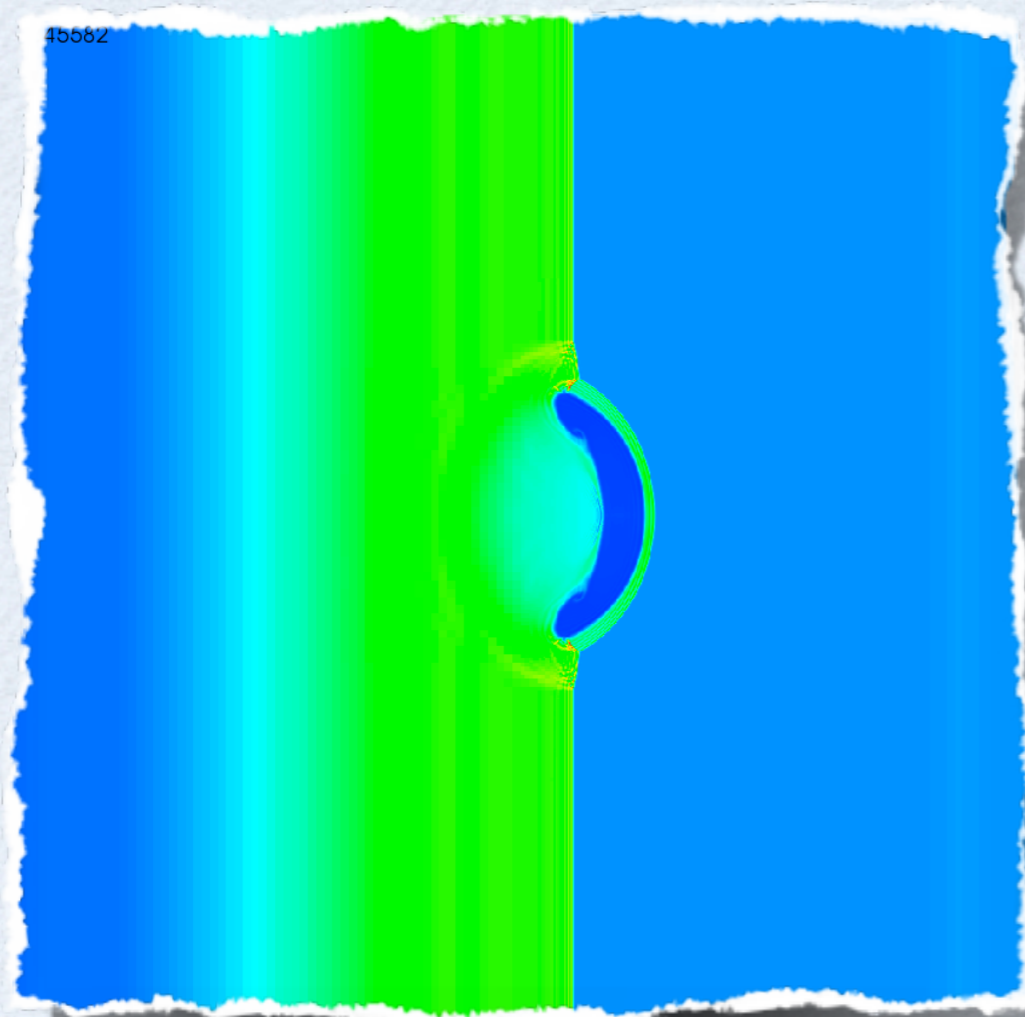
Compared to a space adaptive, single-threaded solver:

- Algorithms : Local Time Stepping: **24X**
- Ghost Reconstruction : CPU optimization (vectorization): **1.8X**
- Ghost Reconstruction : Task-based parallelism (via TBB): **8X** (over 12)
- GPUs as accelerators: **3X**

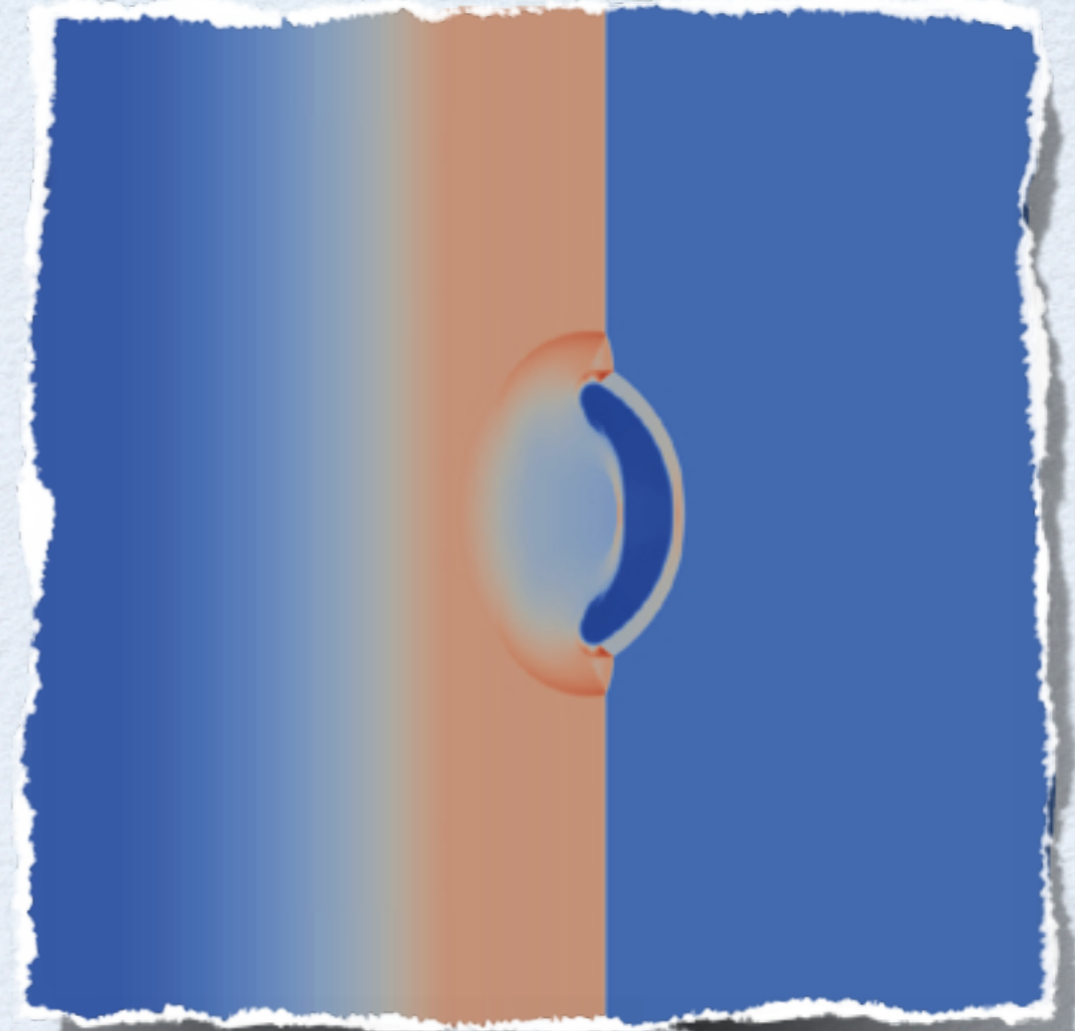
▶ Overall Reduction in time to solution: ~ **1000**

A comparison of CHOMBO vs MRAG

shock-bubble interaction



density field



Chombo:


91 min, 230 MB

single-phase
2nd order PPM

MRAG (home grown, swiss quality stuff):

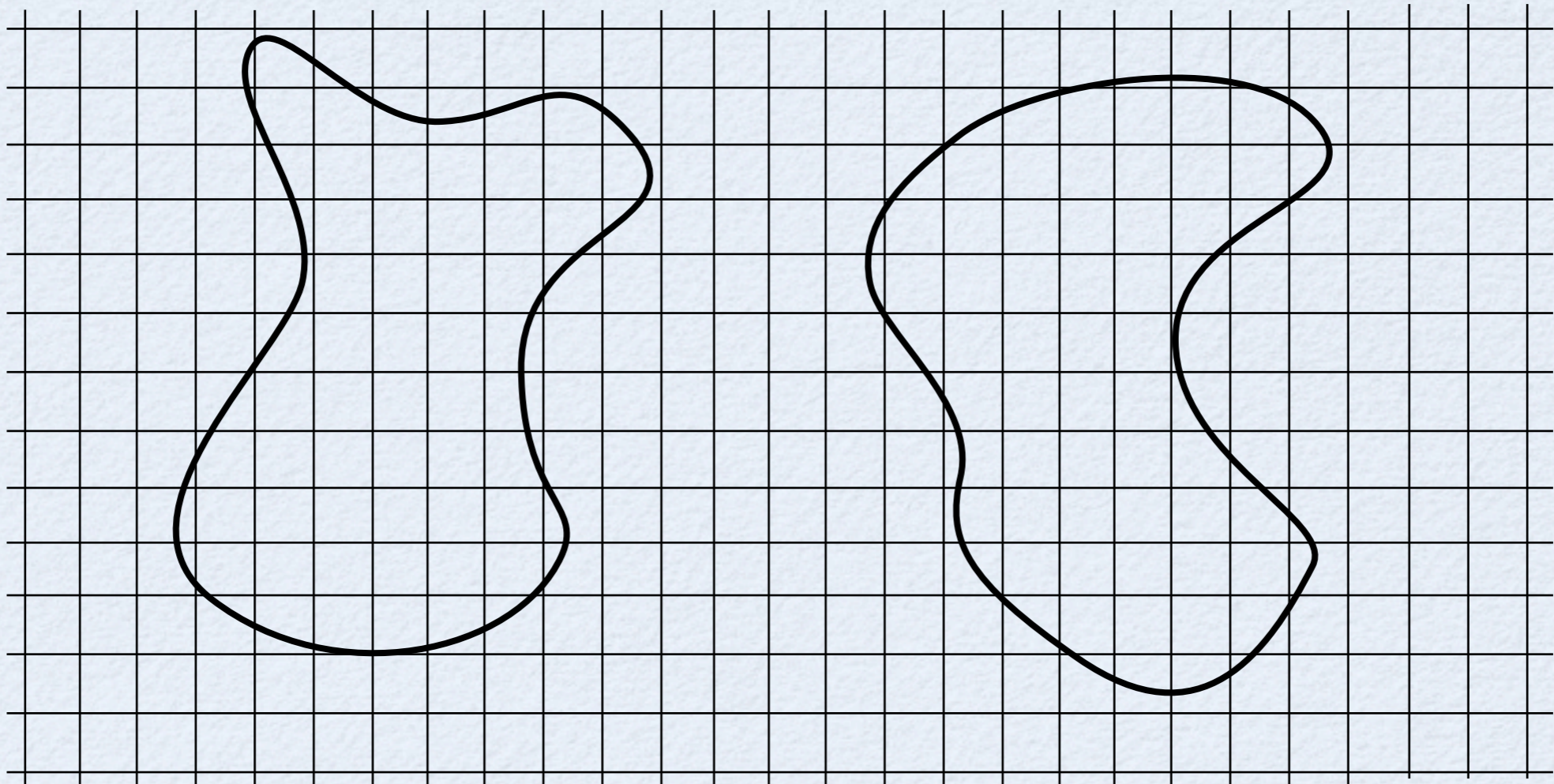
56 min, 244 MB (+ 1 GPU: 7 min)

multi-phase
5th order WENO scheme



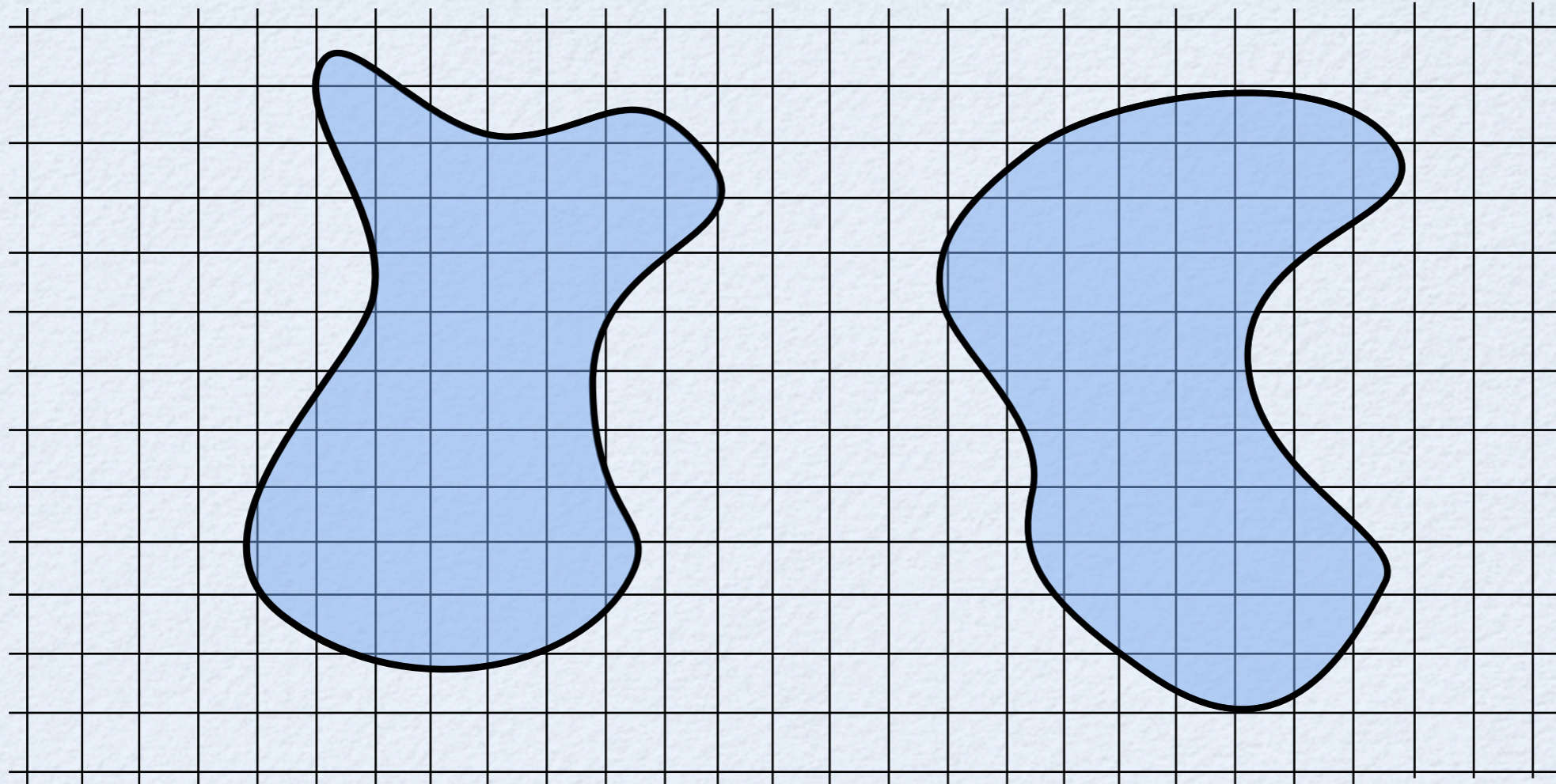
BOUNDARIES + ALGORITHMS

Boundary Conditions = Coupling



$$\rho \frac{D\mathbf{u}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + f \text{ (enforces b.c.)}$$

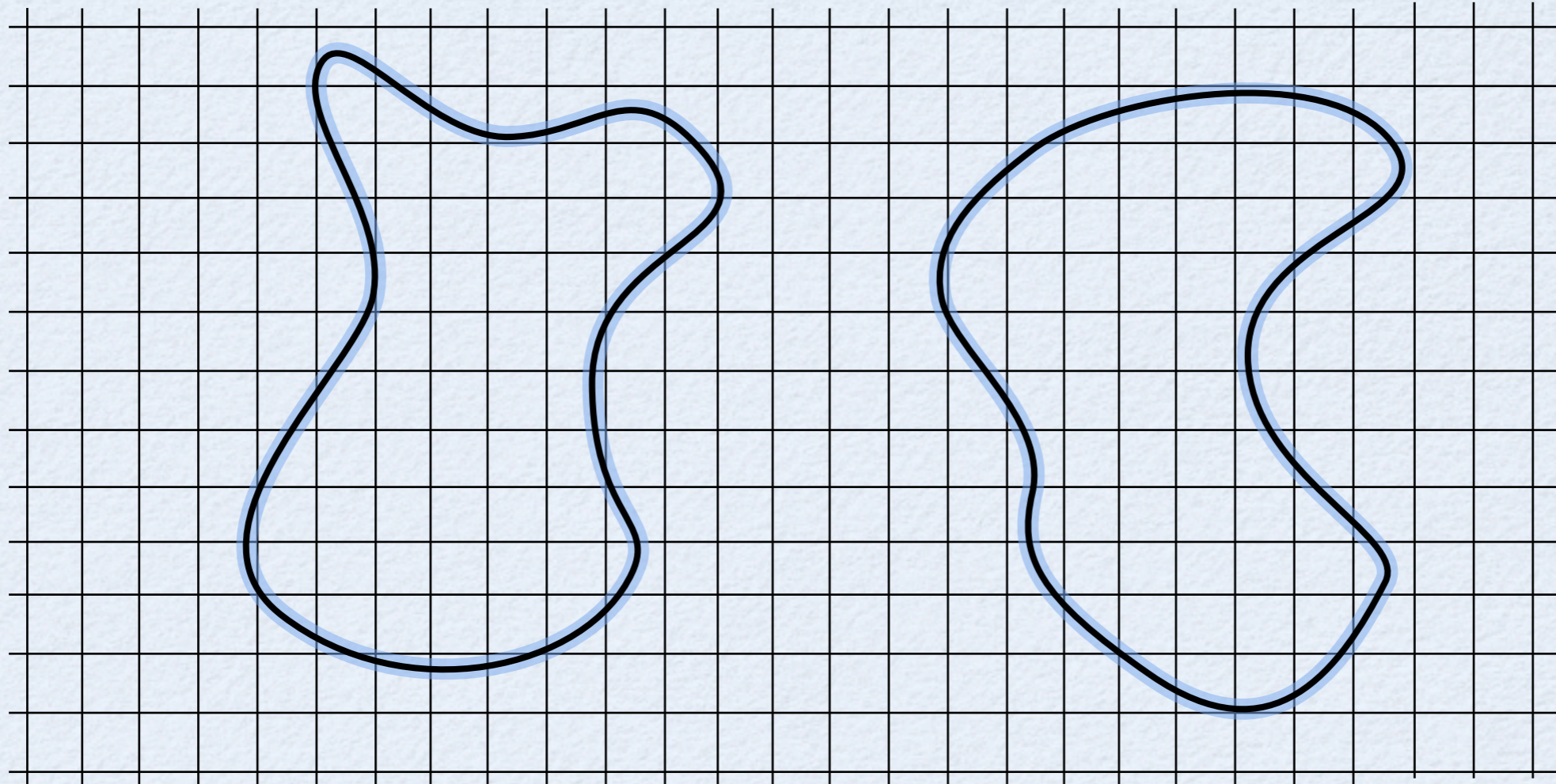
Boundary Conditions = Coupling



$$\rho \frac{D\mathbf{u}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + f(\text{enforces b.c.})$$

Penalization Method: $f(\mathbf{x}) = \lambda \chi_S(\mathbf{u}_S - \mathbf{u})$

Boundary Conditions = Coupling

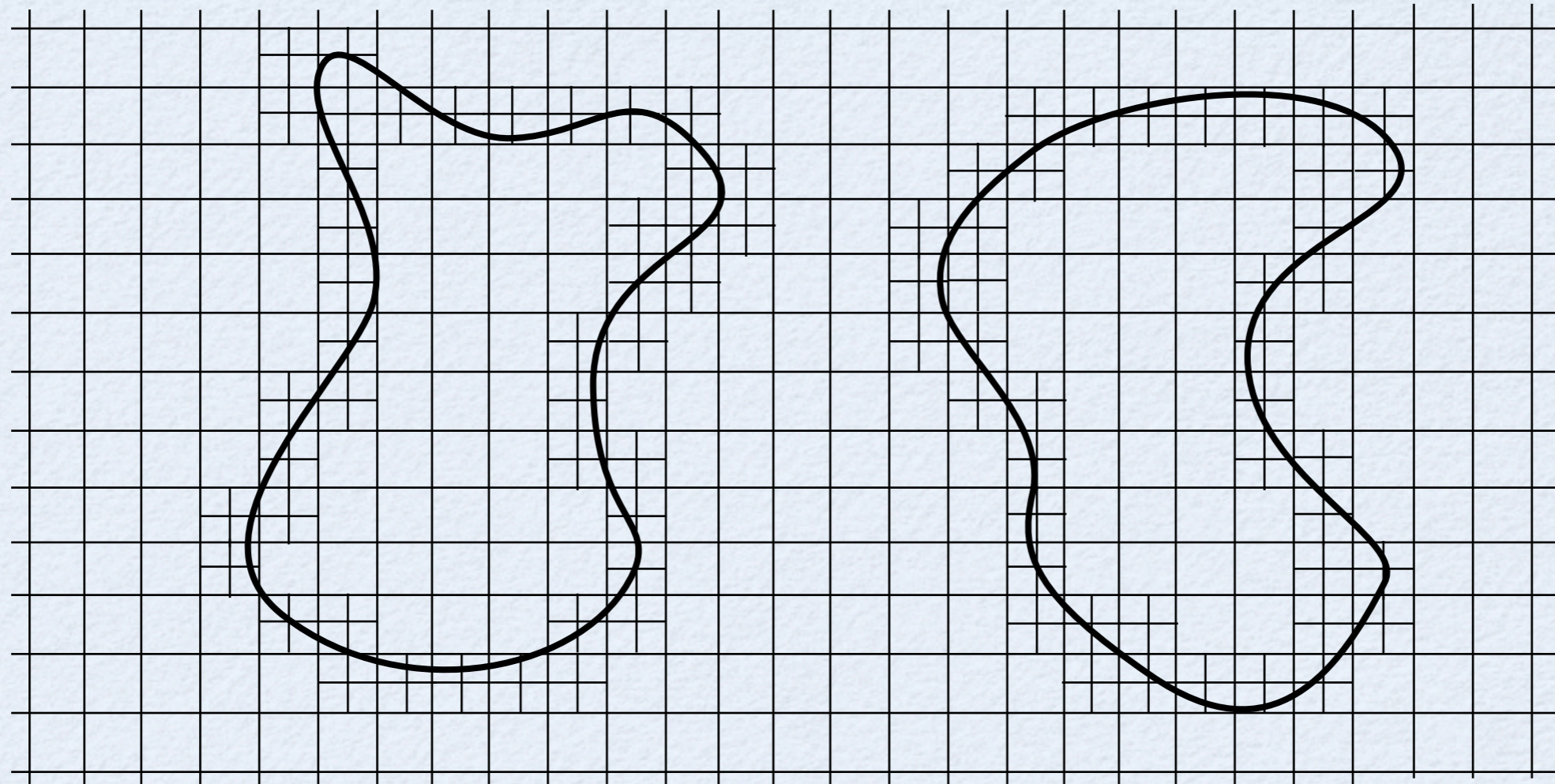


$$\rho \frac{D\mathbf{u}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + f(\text{enforces b.c.})$$

Penalization Method: $f(\mathbf{x}) = \lambda \chi_S(\mathbf{u}_S - \mathbf{u})$

Immersed Boundary Method: $f(\mathbf{x}) = \kappa \delta_S(\mathbf{x}_S - \mathbf{x})$

Boundary Conditions = Coupling

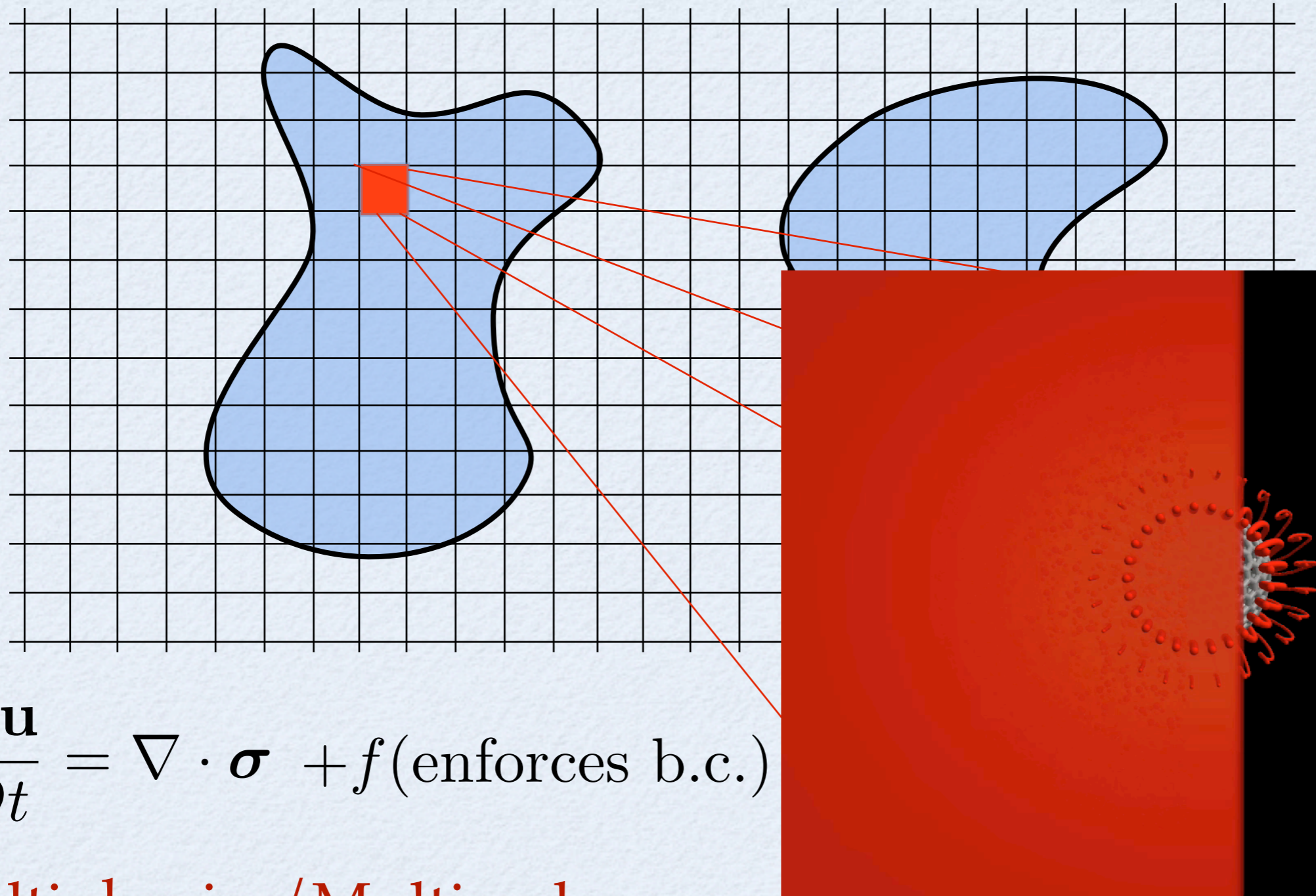


$$\rho \frac{D\mathbf{u}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + f(\text{enforces b.c.})$$

Penalization Method: $f(\mathbf{x}) = \lambda \chi_S(\mathbf{u}_S - \mathbf{u})$

Immersed Boundary Method: $f(\mathbf{x}) = \kappa \delta_S(\mathbf{x}_S - \mathbf{x})$

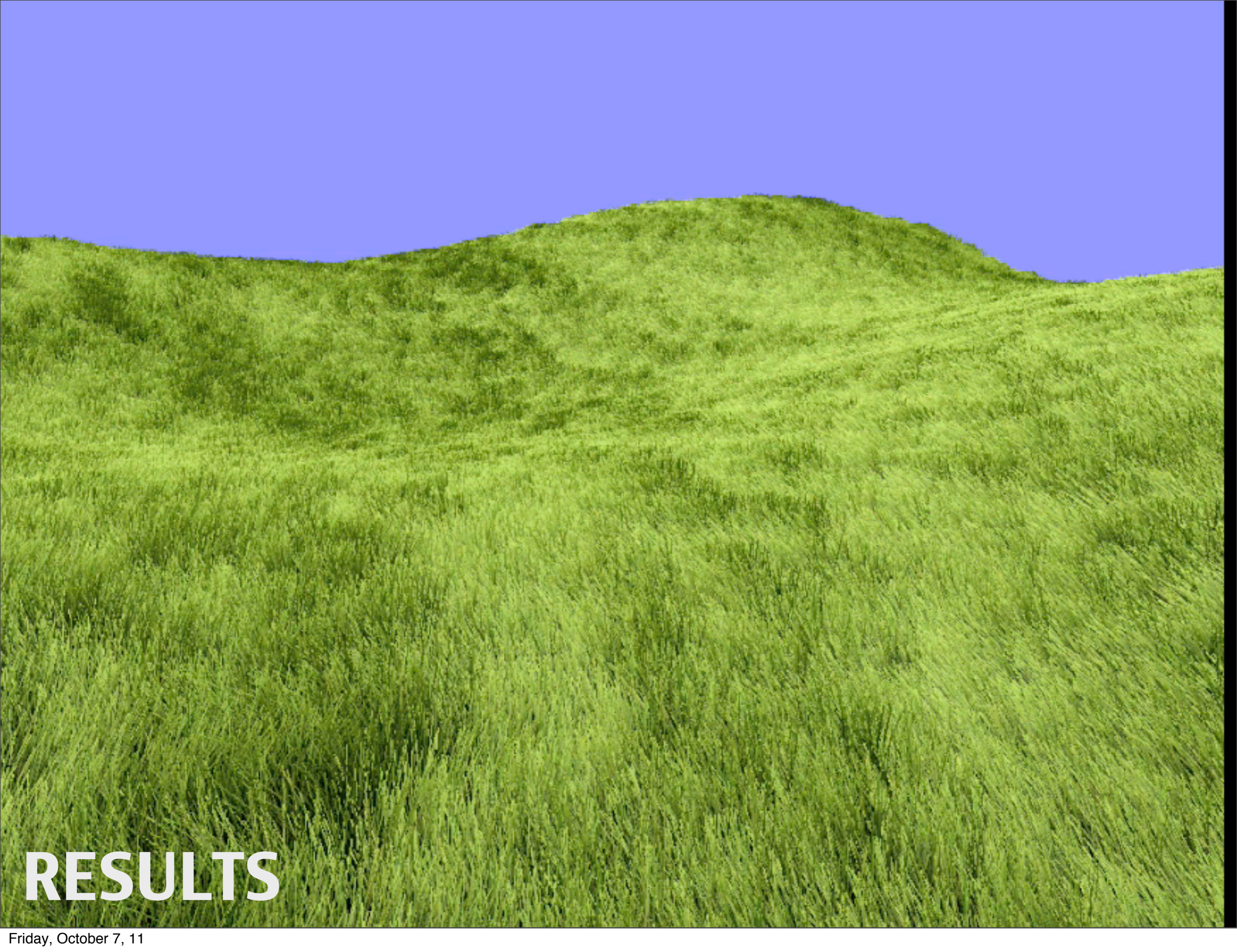
Boundary Conditions = Coupling



$$\rho \frac{D\mathbf{u}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + f(\text{enforces b.c.})$$

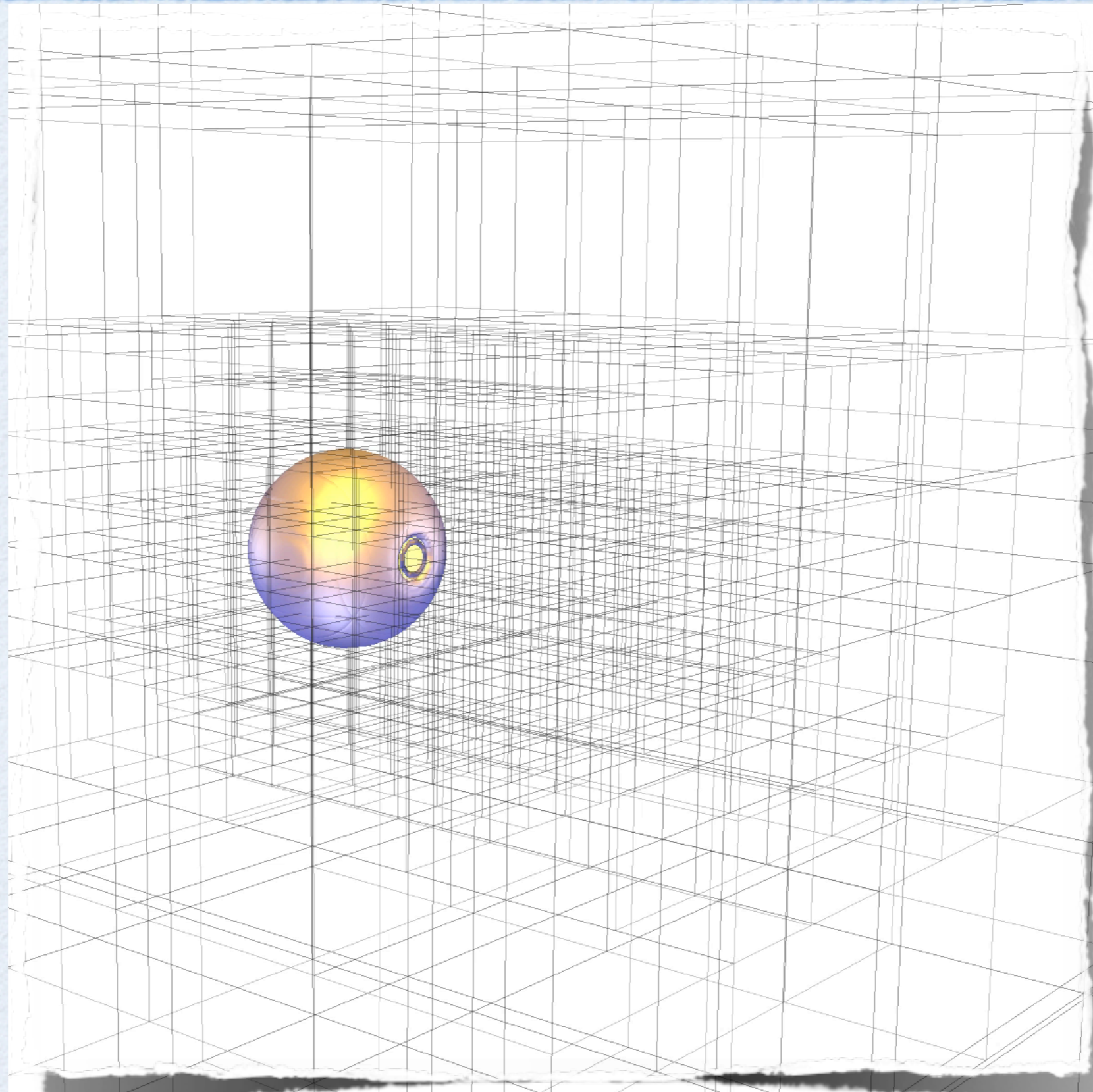
Multiphysics / Multiscale

$f(\mathbf{x}) = (\text{result from Molecular Simulations})$



RESULTS

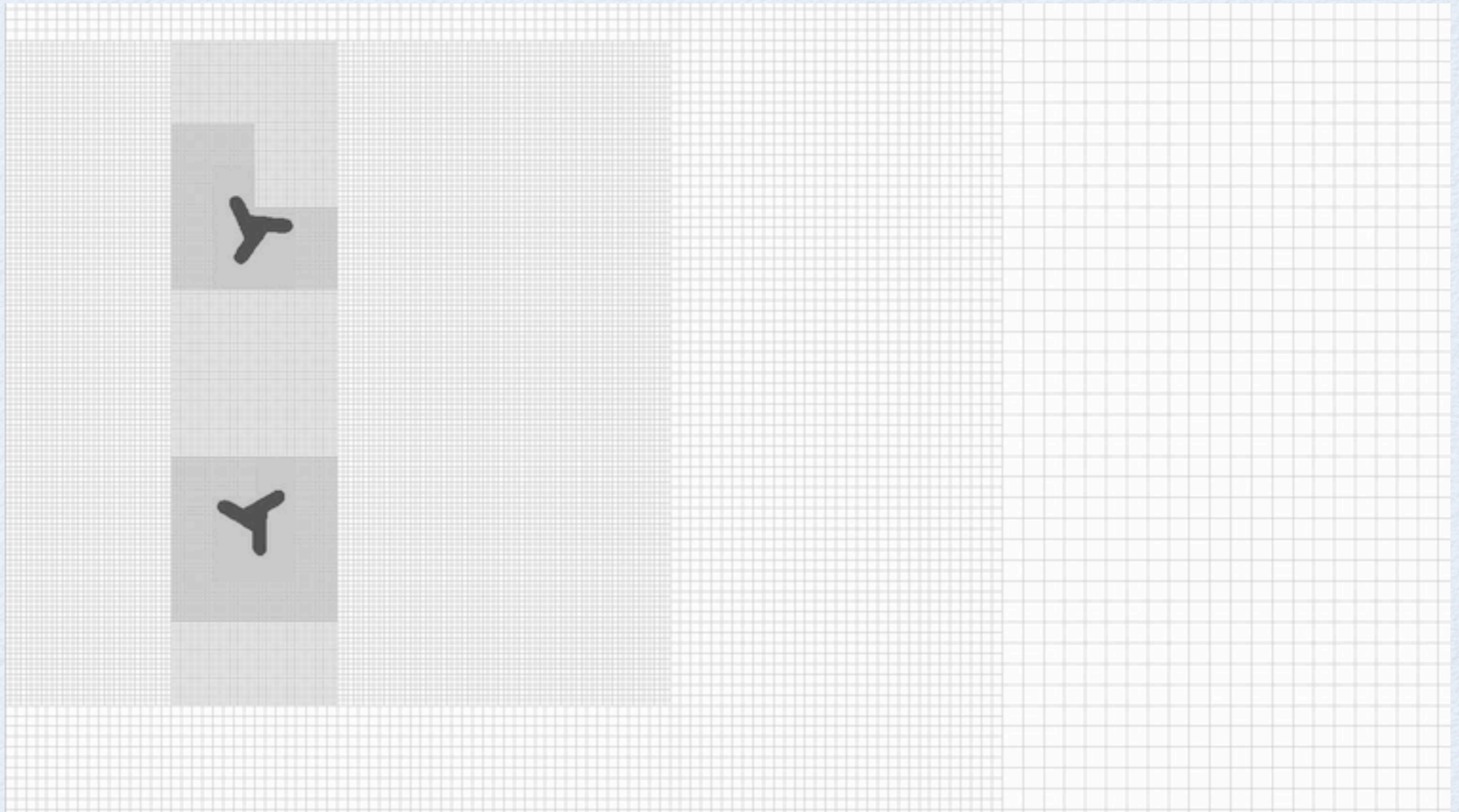
SPHERE @ $Re = 1000$ with Effective Resolution 1024^3



**TIMINGS : 4 days on 3
cores, 2.4 GHz - OpenM
and MPI and TBB**

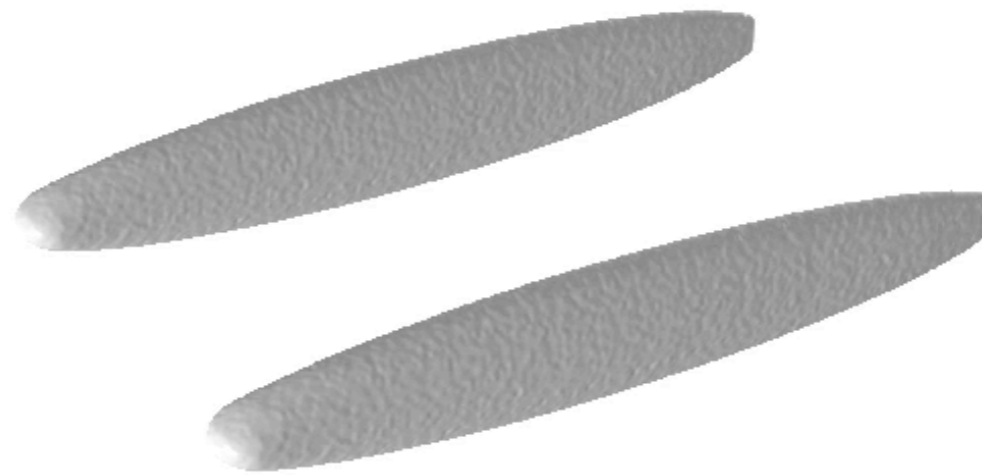
Multi-body Simulations

TIMINGS : 3 hours on 16 cores
- TBB = SSE - Solver reaches
70% of the peak performance
180 GFlops over 210



Fish Schooling

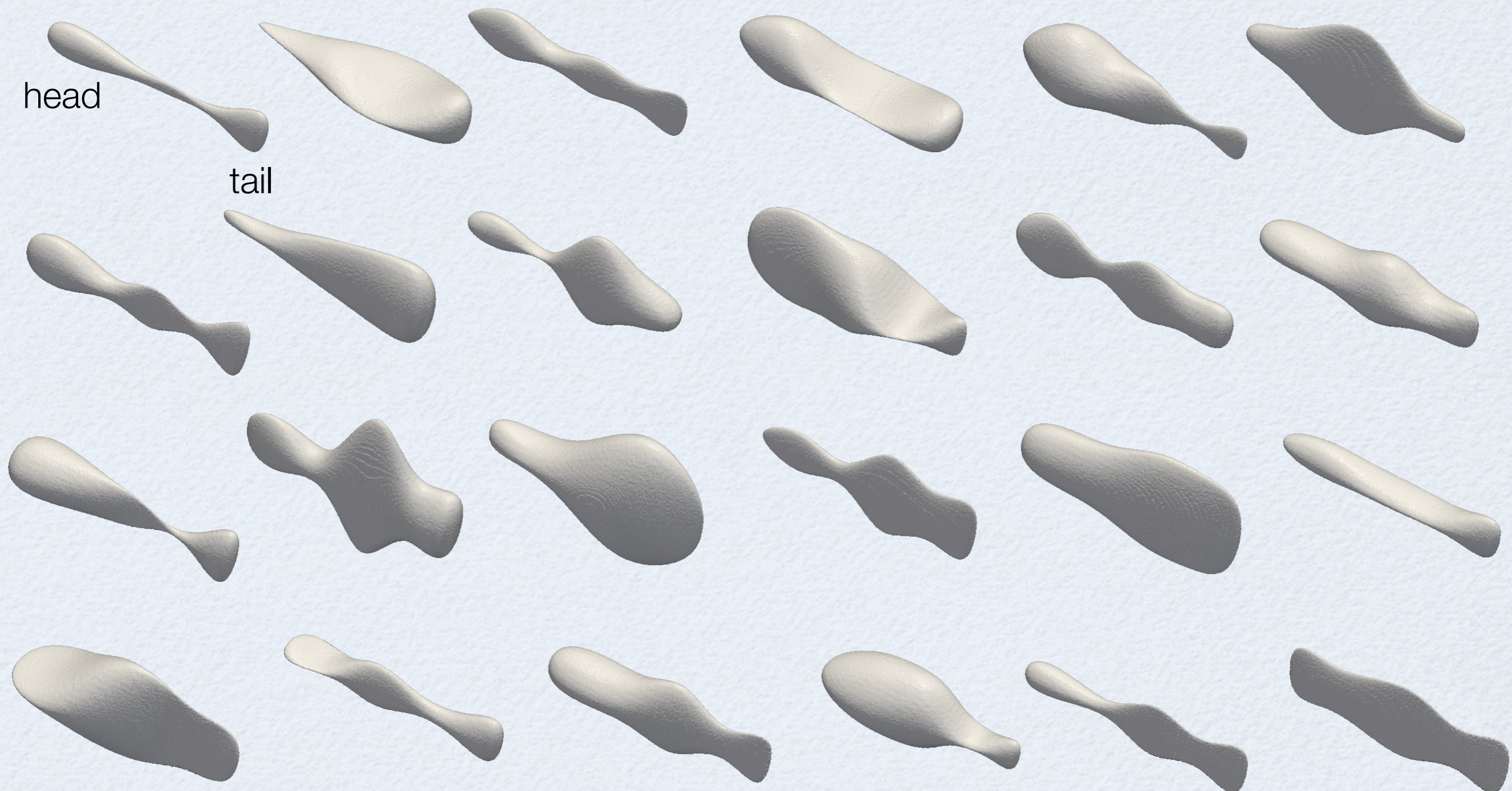
Gazzola M., Chatelain P., van Rees W.M., Koumoutsakos P., Simulations of single and multiple swimmers with non-divergence free deforming geometries, **J. of Comput. Physics**, 2011



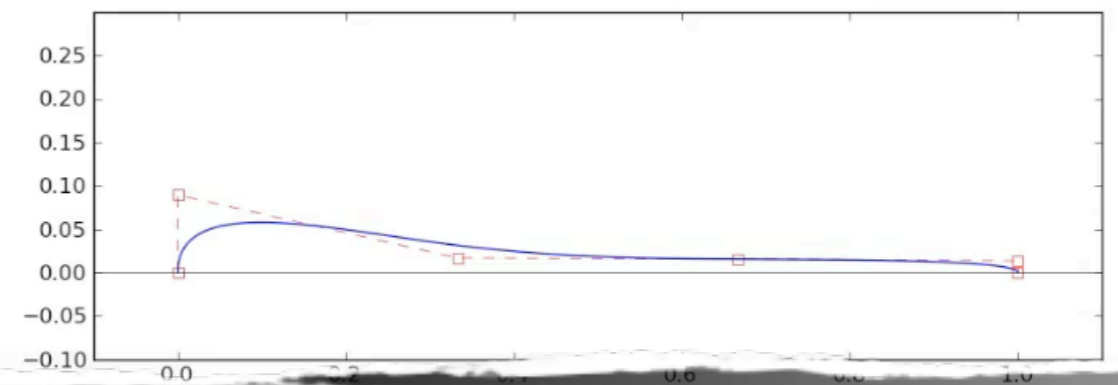
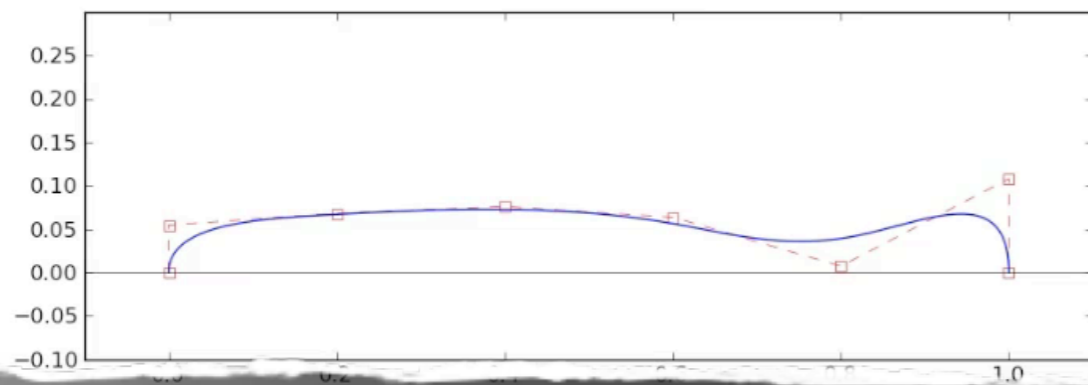
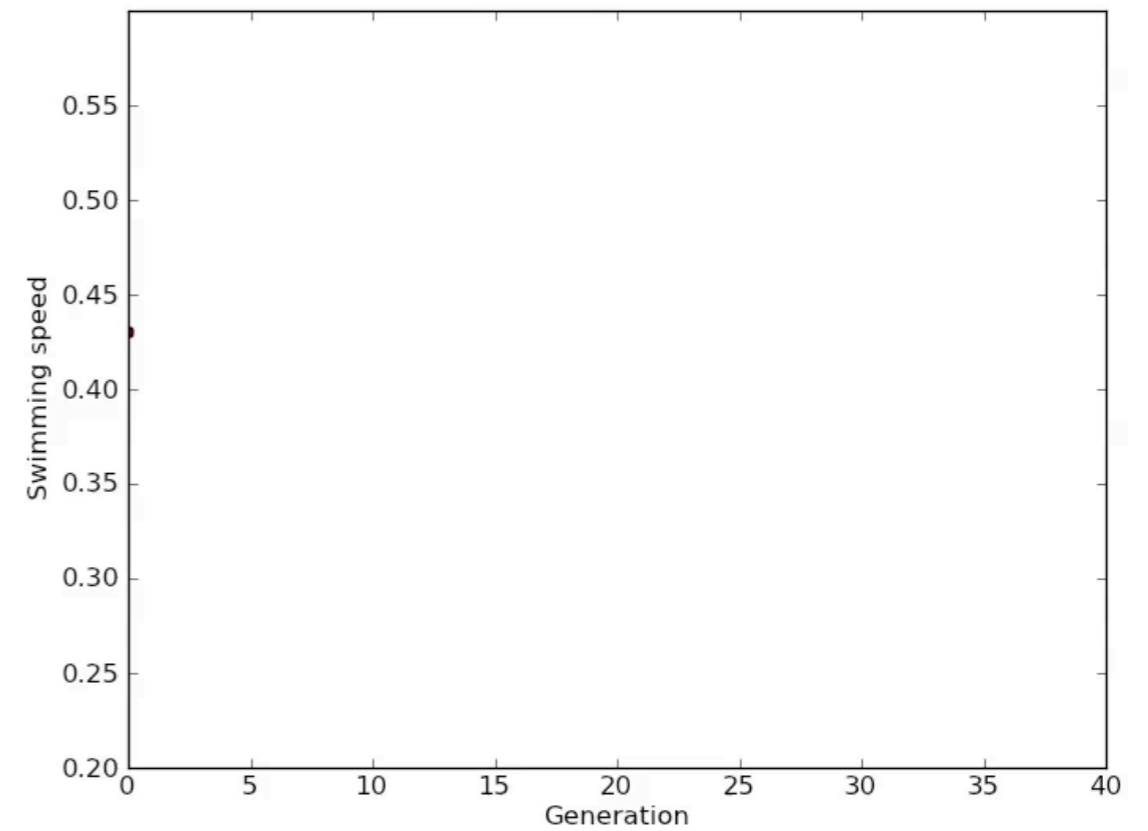
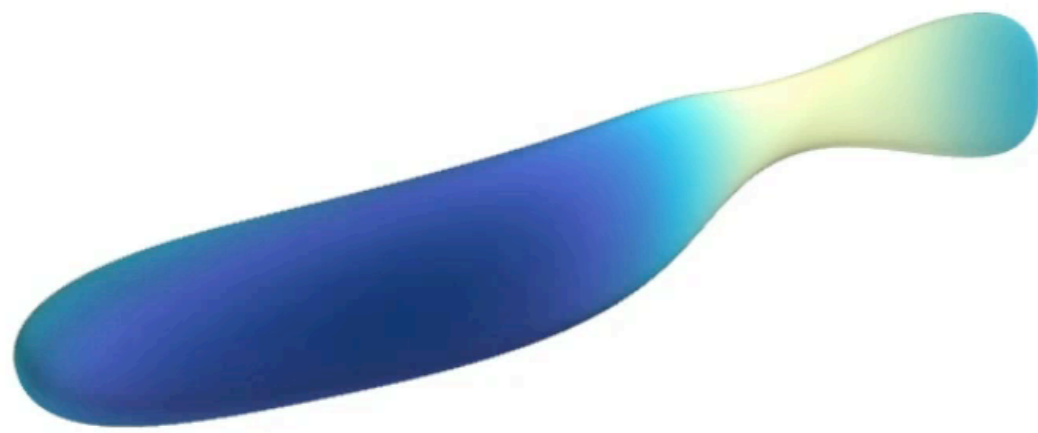
2 FISH (OBVIOUSLY)

Fast Swimmers

Shape Optimization

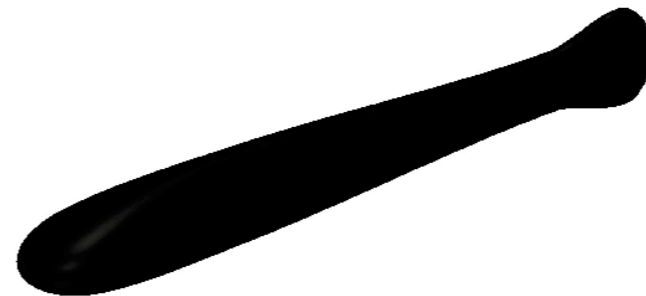


Mean Shape During Evolution



How to escape fast ?

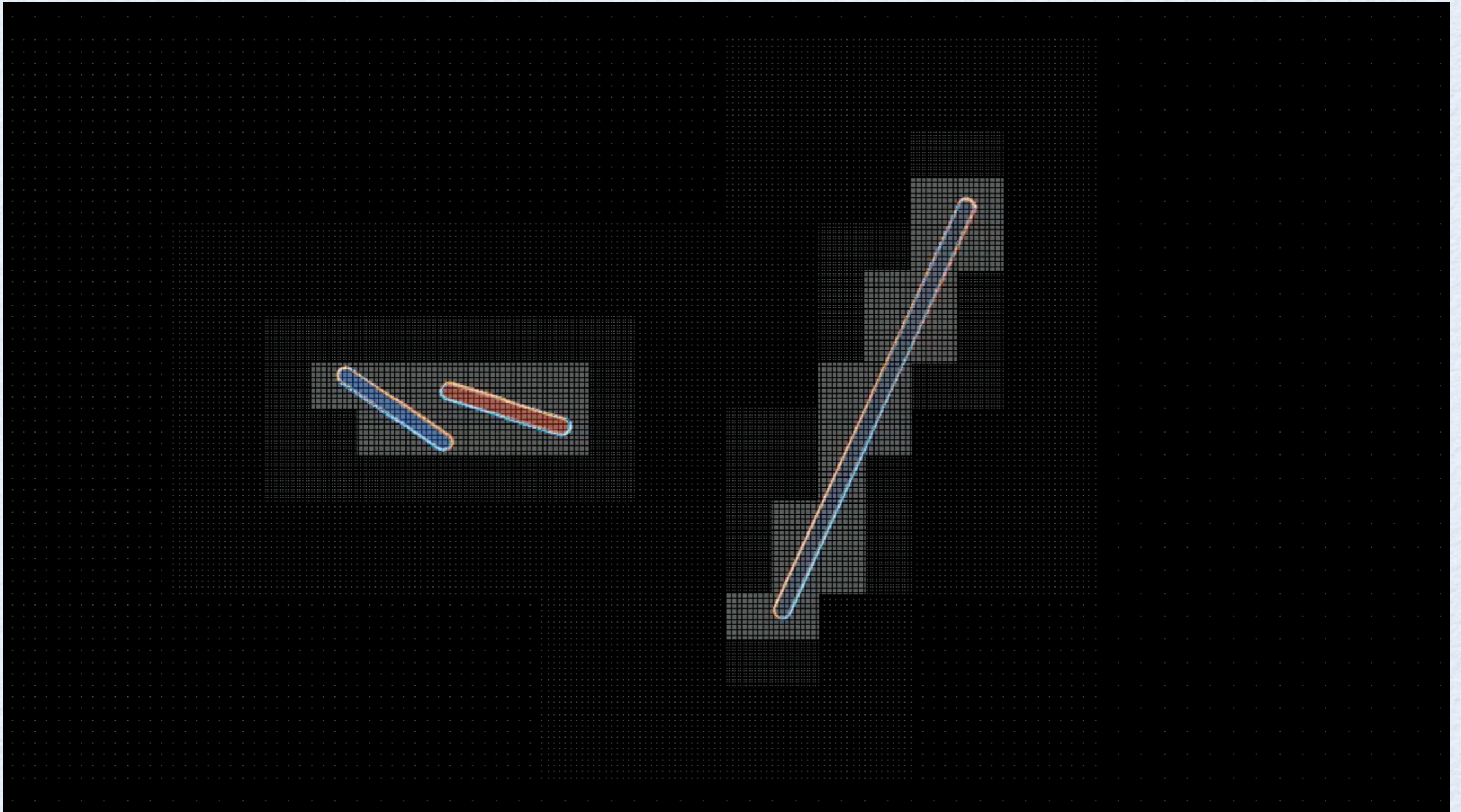
Best Result of an Optimization for escape speed



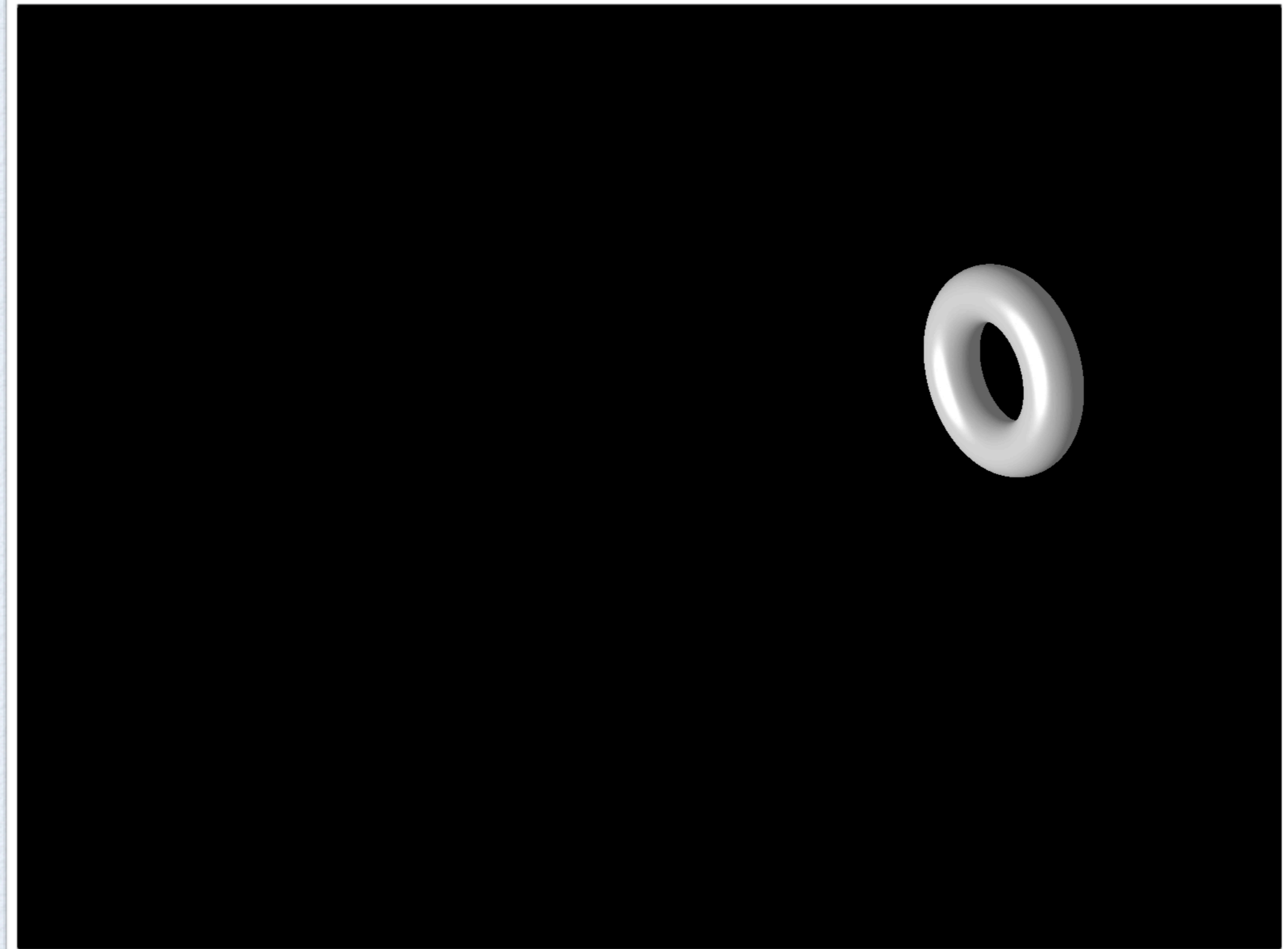
COMPRESSIBLE FLOWS

Brinkman Penalization for
Compressible Flow

Moving Boundaries



Shock – Ballut Interactions



Biological and medical simulations



J. Folkman:

A key transition in the development of tumors is the recruitment of a vasculature

A Model of Sprouting Angiogenesis

Mechanism:

endothelial cells migrate towards source of growth factors

- form cords
- proliferate
- branch / fuse

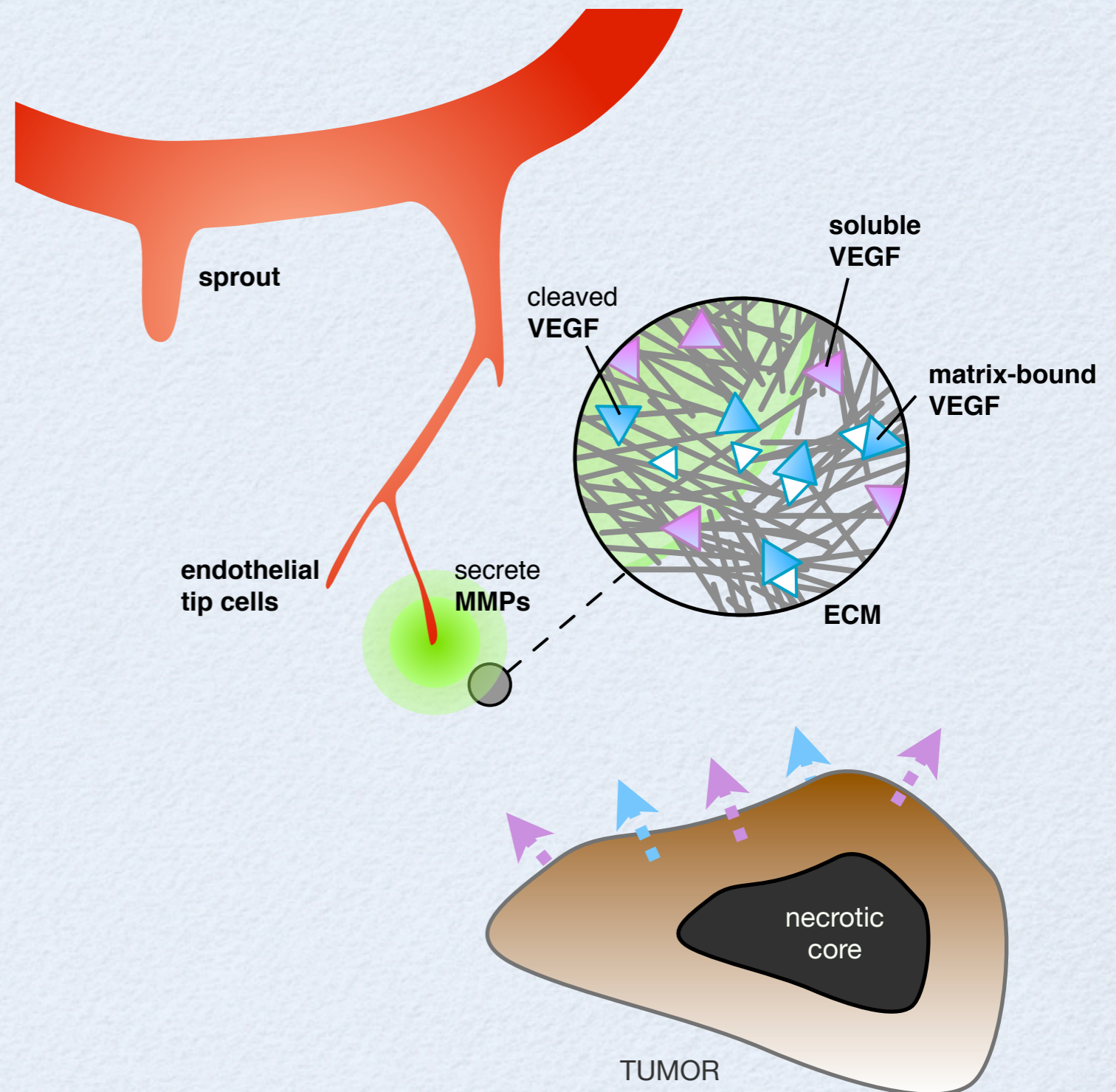
Growth factor: VEGF

exists in two forms:

- soluble
- bound to the matrix (bVEGF)

Release of bVEGF

endothelial cells secrete proteinases
proteinases cleave bVEGF → soluble



Multi-scale Modeling of Angiogenesis

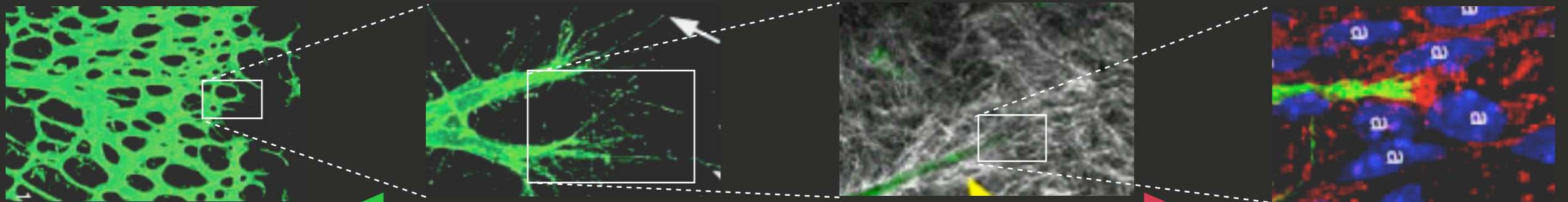
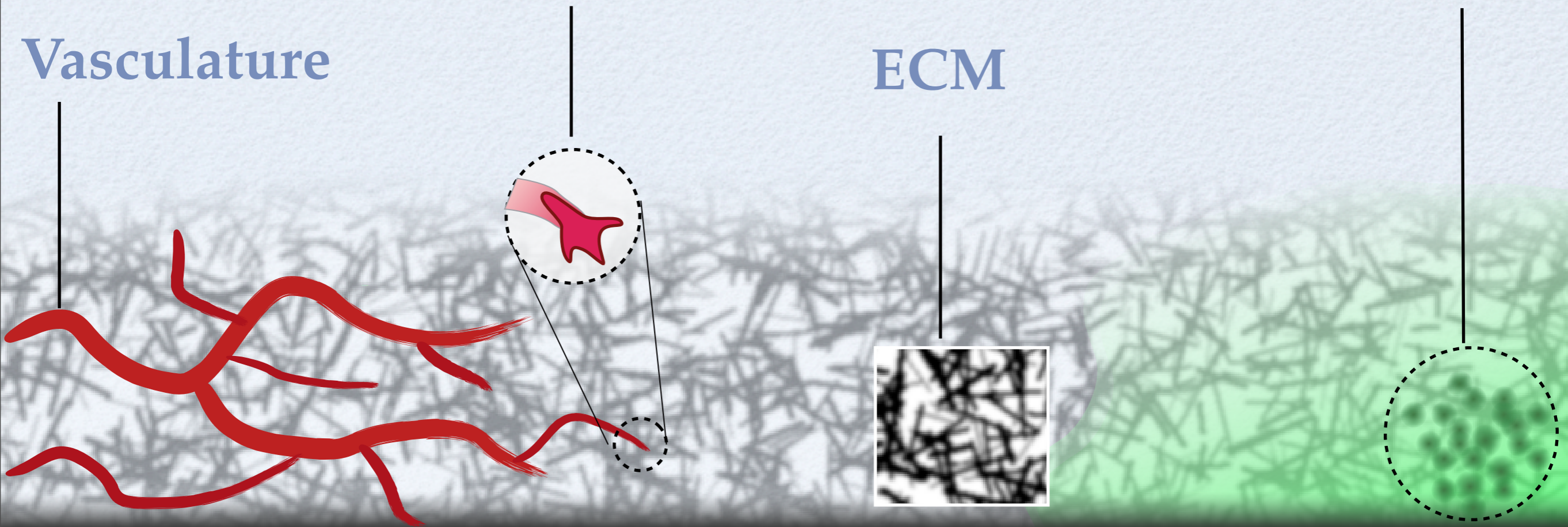
Milde F., Bergdorf M.,
Koumoutsakos P., A Hybrid
Model for 3D Simulations
of Sprouting Angiogenesis,
Biophysical J.,2008

Tip Cell

Growth Factors

Vasculature

ECM



Scale

[1] H. GERHARDT, M. GOLDING, M. FRUTTIGER, C. RUHRBERG, A. LUNDKVIST A. ABRAMSSON, M. JELTSCH C. MICHELL, .ALITALO, D. SHIMA AND C. BETSHOLTZ, VEGF GUIDES ANGIOGENIC SPROUTING UTILIZING ENDOTHELIAL TIP CELL FILOPODIA, J. CELL. BIOL., 2003

Modeling the Matrix

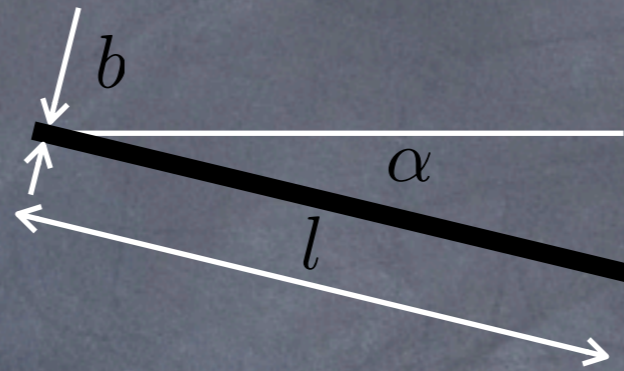
Fibers:

- straight
- random direction
- distribution of lengths

$$l = l_0 2^m z$$

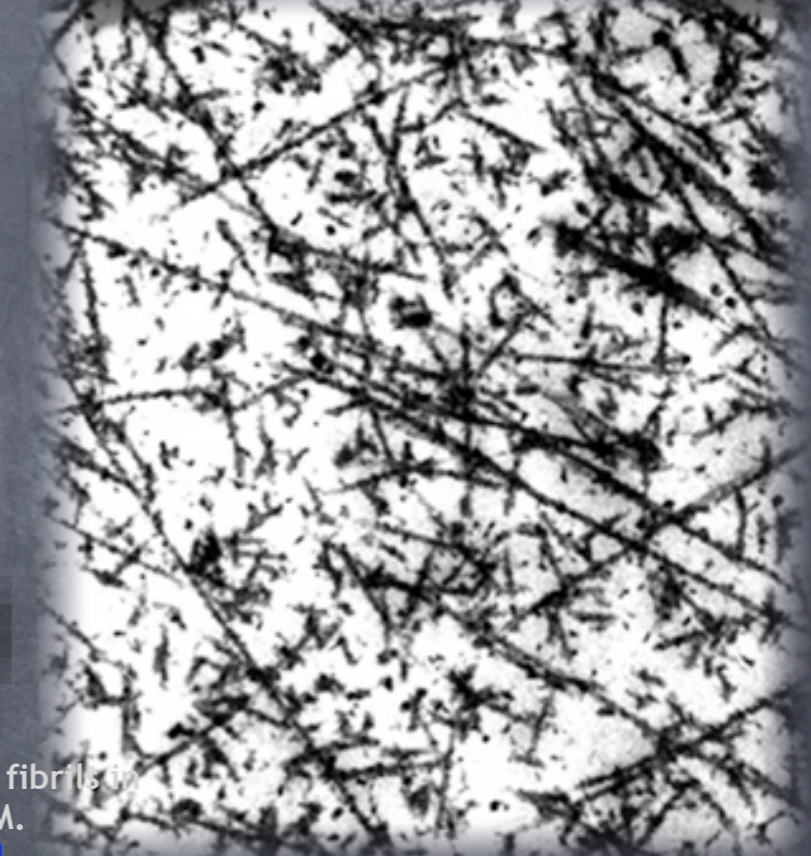
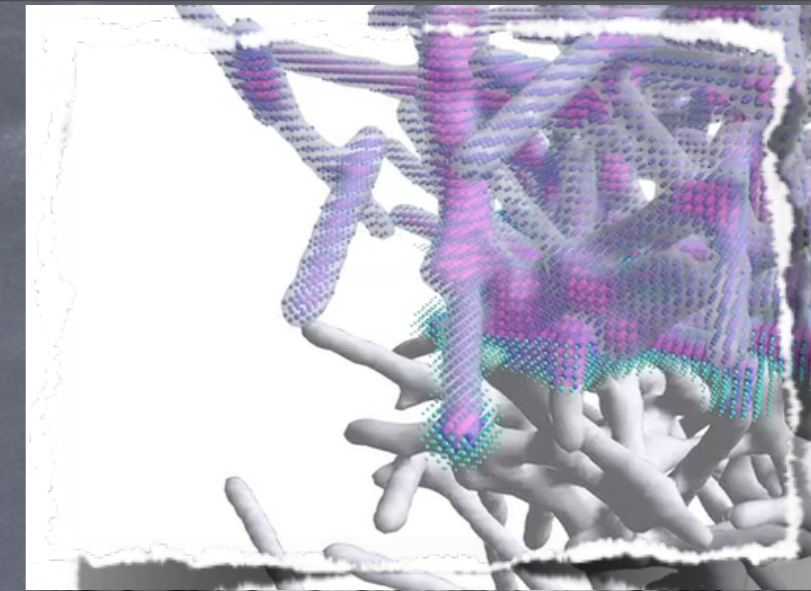
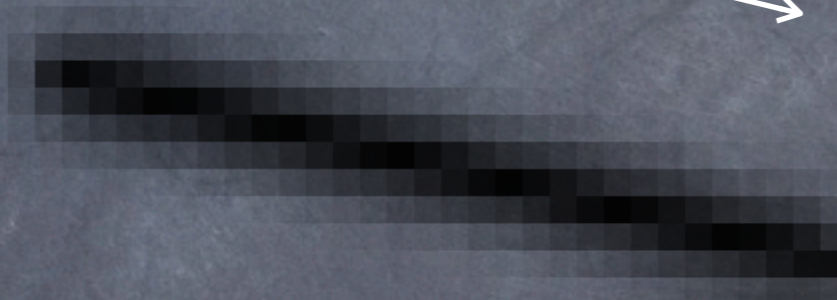
$$\alpha \in \mathcal{U}([0, \pi])$$

$$z \in \mathcal{N}(0, 1)$$



Indicator field : e

- unity where fibers present
- smoothed (implicit filopodia)



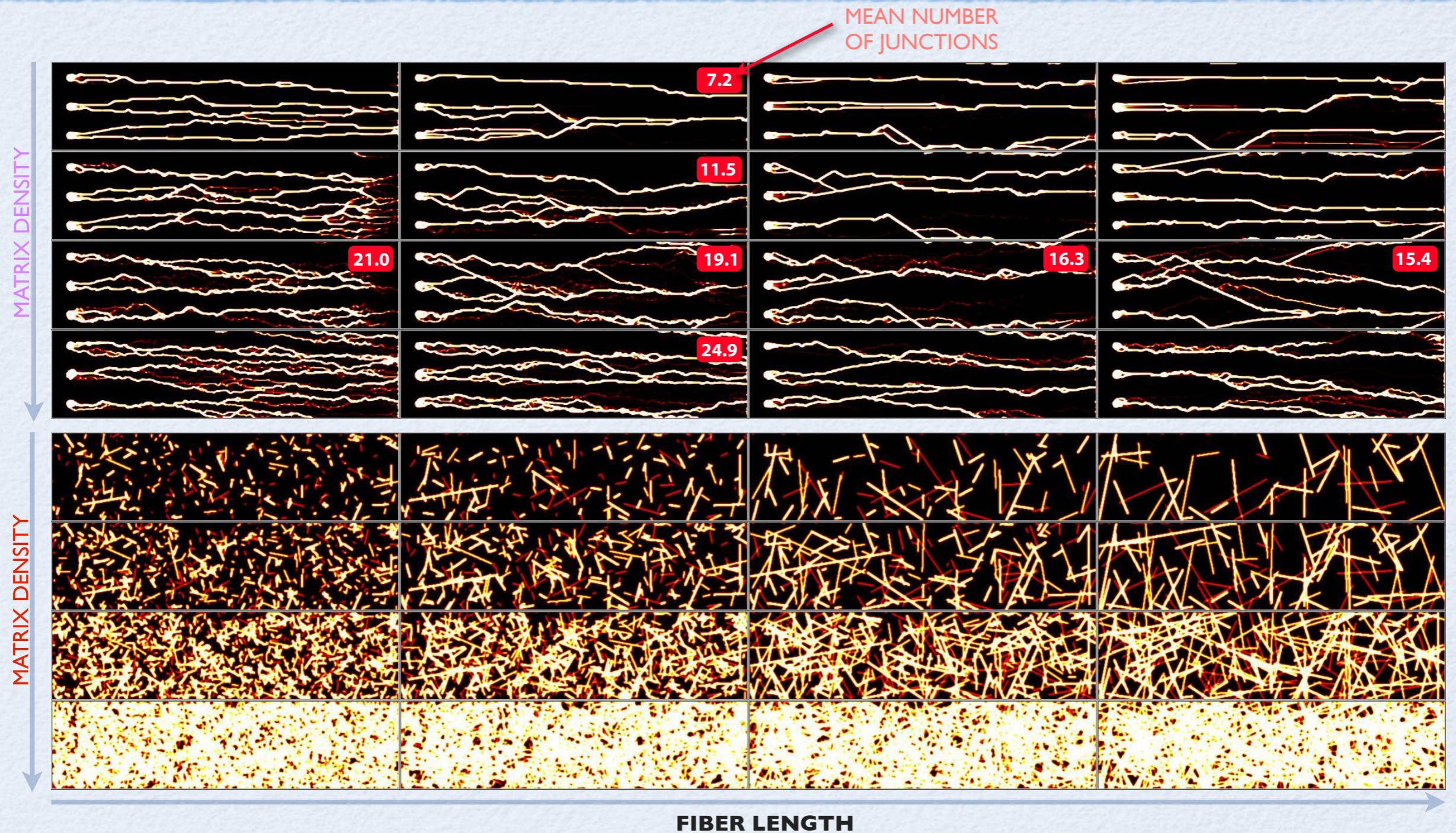
Randomly oriented collagen fibrils in cartilage ECM imaged by TEM.
<http://www.shcc.org>



Angiogenesis : *in silico*



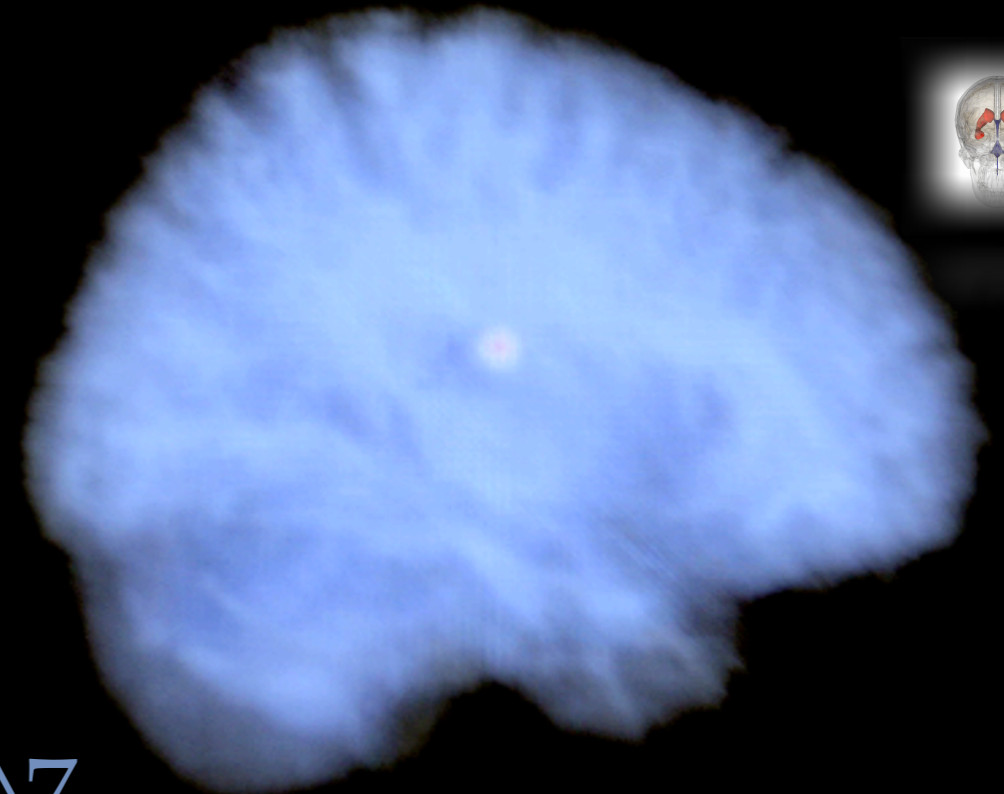
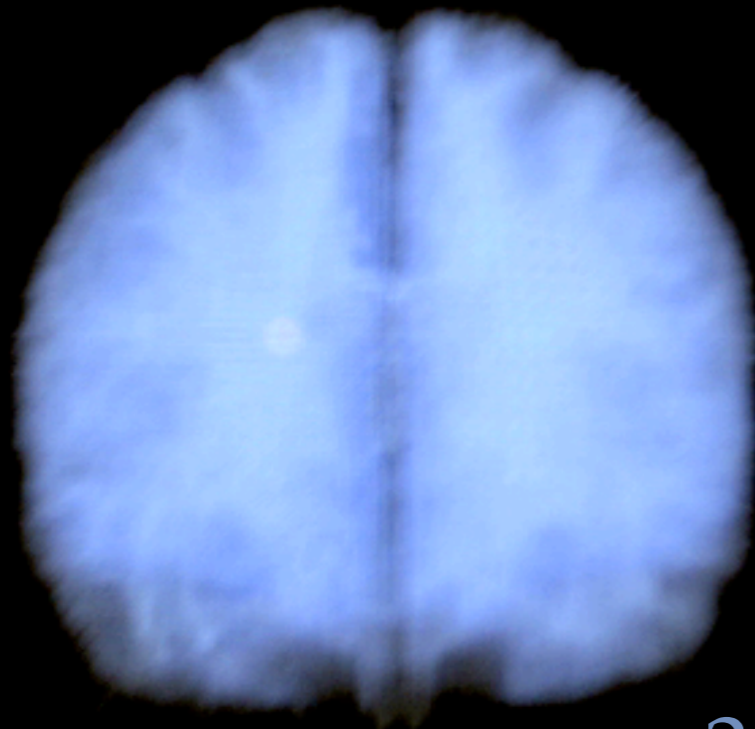
Effect of Matrix structure on branching



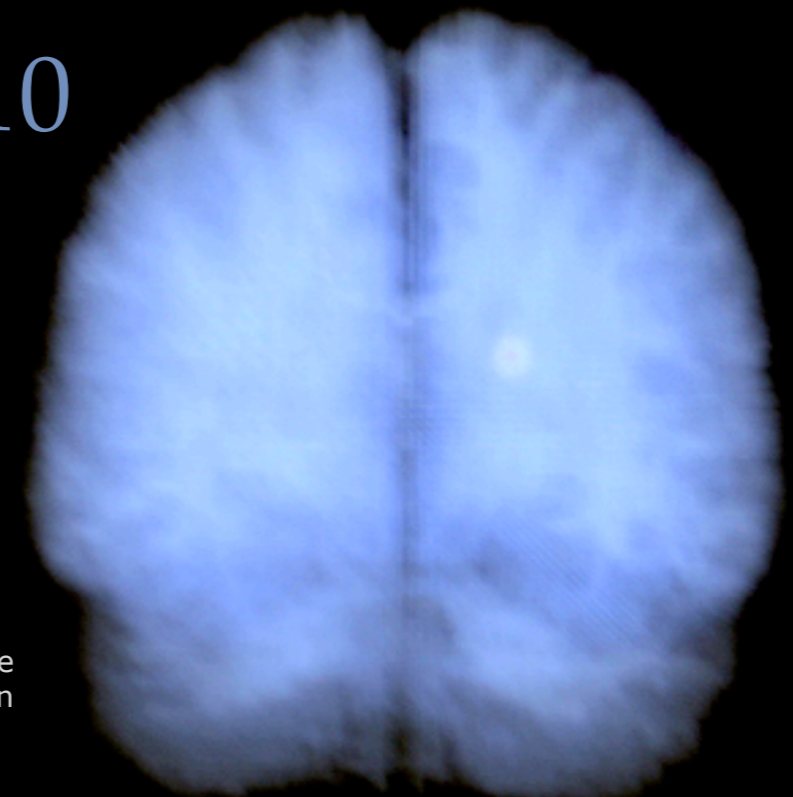
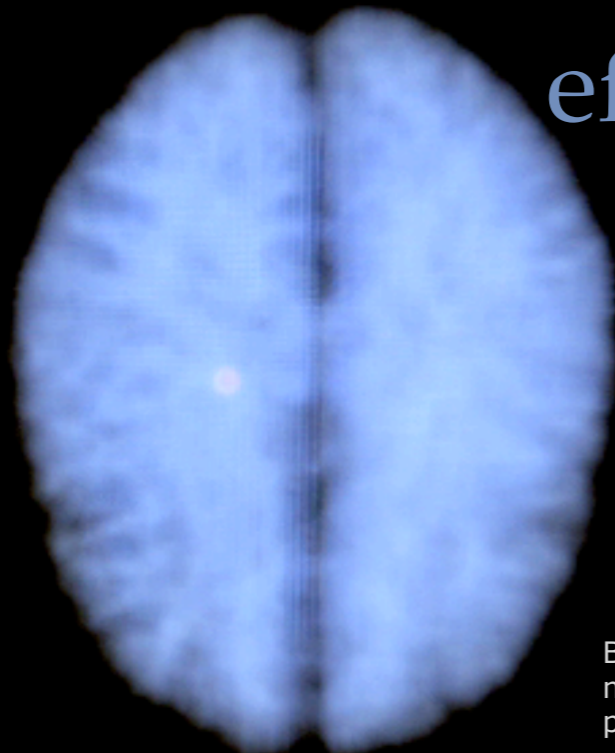
statistics over n = 50 different matrices
junctions identified with AngioQuant

Spatially Adaptive Stochastic Simulations of Gliomas

Time: 0.00 years



actual $M = 10^7$
effective $M = 10^{10}$



Bayati B., Chatelain P., Koumoutsakos P., Adaptive mesh refinement for stochastic reaction-diffusion processes, **J. of Comput. Physics**, 2011



Last Words

CHALLENGES

- Fast and/or Green Multi-scale Algorithms
- SIMULATIONS ARE DATA : UQ_{+P}

APPLICATIONS

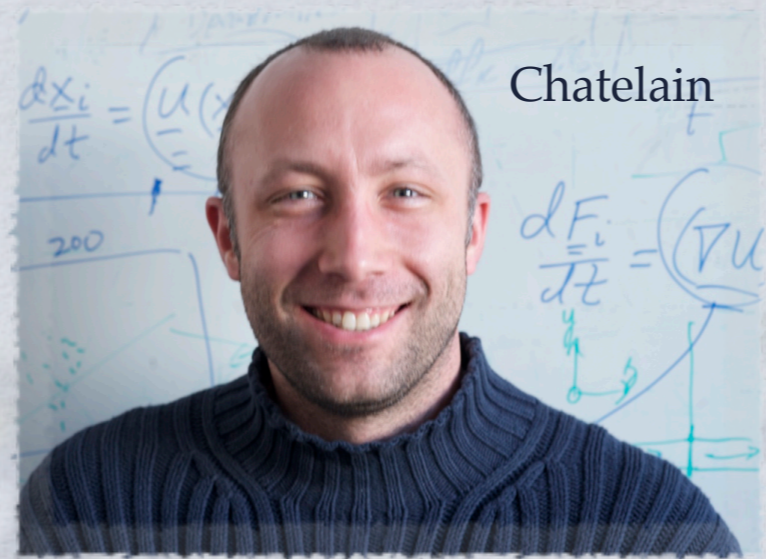
- Biology, Nanotechnology and Fluids : Bridge Gaps and Disciplines

THANKS

- ETHZ + CSCS
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- EU
- NVIDIA (ETHZ a CUDA Research Center)



Walther



Chatelain



Bayati



Bergdorf



Rossinelli



Gazzola



Hedjazialhosseini



van Rees



Milde